

Precyzyjna astrometria i geodezja

Prezentacja na seminarium
Fale Grawitacyjne
Warszawa, 18 XII 2009

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Techniki i dokładności pomiarów

Układy odniesienia na niebie

ICRF(1) i jego rozszerzenia

ICRF2 – katalog radioźródeł (2010)

Przykłady pomiarów baz VLBI

Ziemi uklad odniesienia (ITRF)

Ruchy stacji pomiarowych

Ruchy względem płyt tektonicznych
(świat, Europa, Włochy)

Produkty IVS/IERS

Nutacja

Ruchy bieguna Ziemi

UT1 – UTC

Sekunda przestępna

O toruńskim Centrum Astronomii

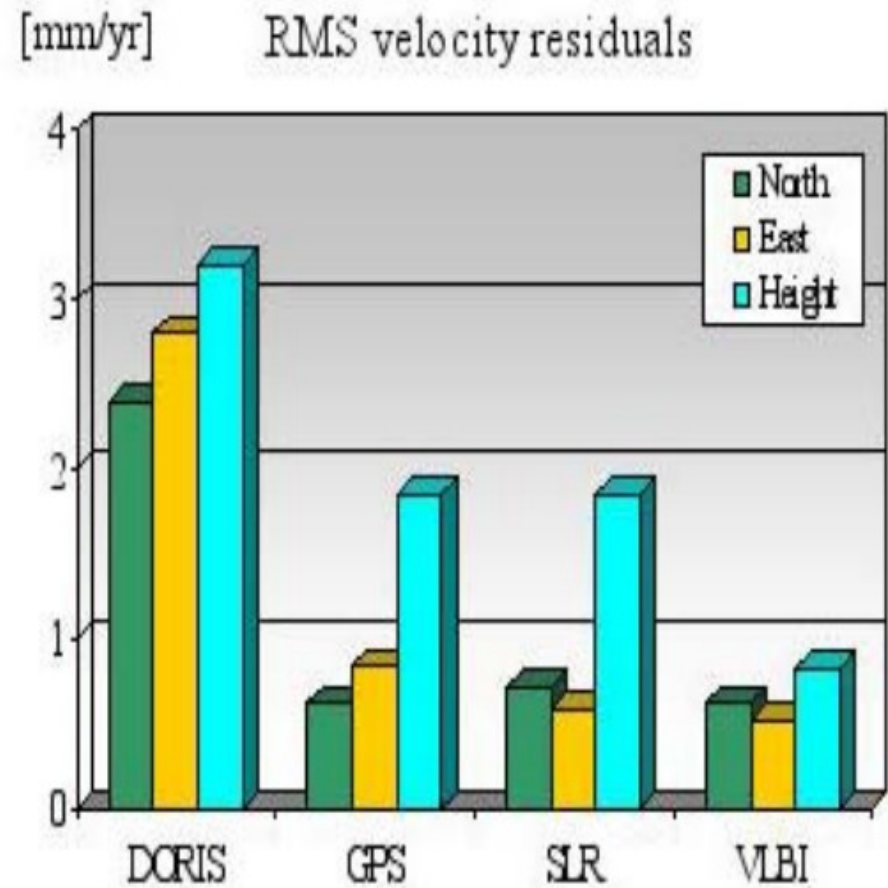
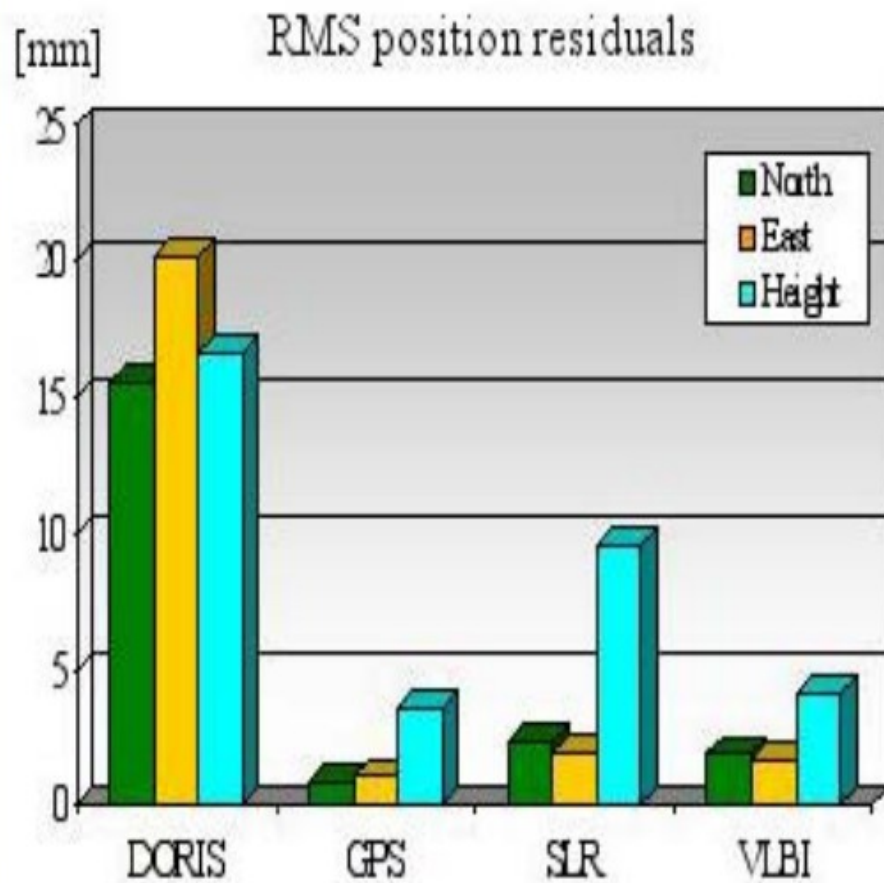
RT32

OCRA

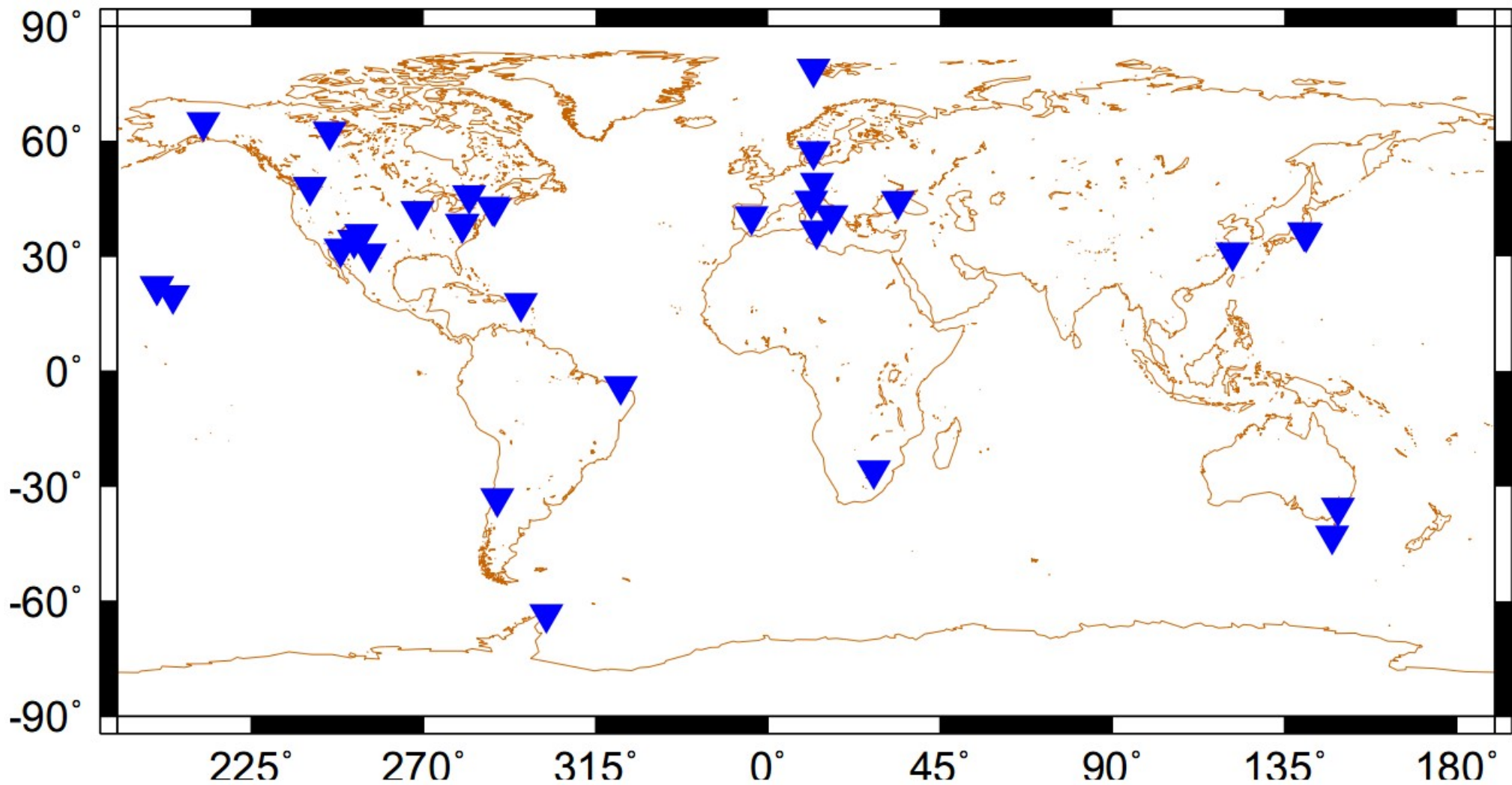
PIAST

RT100

RMS of Space Geodetic Techniques



(From a global TRF solution derived by DGFI, Munich)



Geodetic VLBI Network

IVS products for the CRF

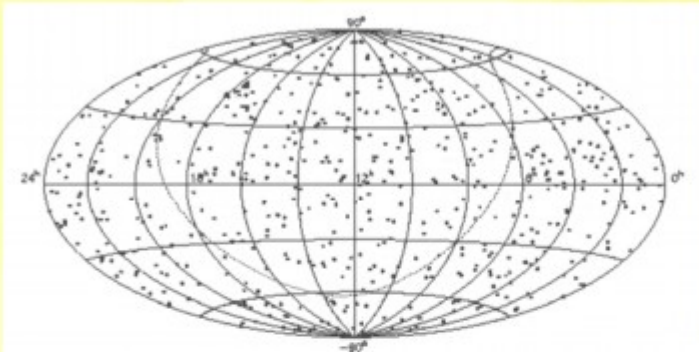
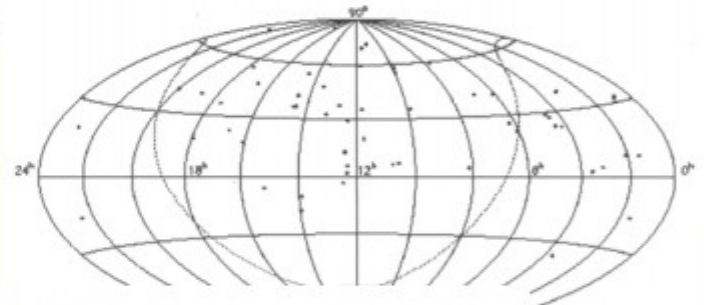


Figure 1: Distribution of the 608 ICRF sources on an Aitoff
The dotted line represents the G



projection of the celestial

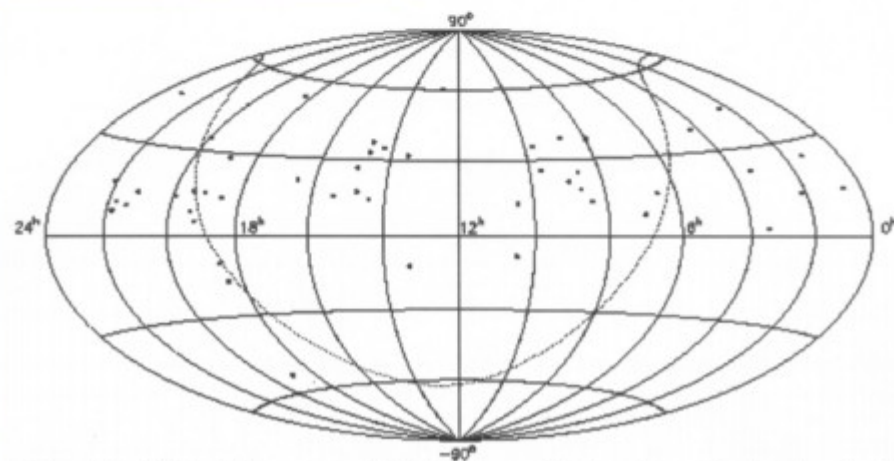


Figure 4: Distribution of 50 new sources in ICRF-Ext.2 on an Aitoff equal-area projection of the celestial
sphere. The dotted line represents the Galactic equator.

- ICRF
 - CRF (Ma, et al., 1998)
 - 212 defining sources
 - 294 candidate sources
 - 102 other sources
 - ICRF-Extension 1 (IERS, 1999)
 - completed 1999
 - adding 59 sources
 - ICRF-Extension 2 (Fey et al., 2004)
 - completed 2002
 - adding 50 sources

ICRF2

VLBI Catalogue of Compact Radio Sources

The Second Realization of ICRS

- ❖ ICRF is currently **defined** by radio positions of 295 extragalactic objects.
- ❖ The ICRF2 catalogue is the most complete. It includes 3414 (295+922+2197) sources sufficiently observed with astrometric and geodetic VLBI from August 1979 to March 2009.
- ❖ On 13 August 2009 it has been adopted by the IAU as the fundamental realization of the ICRS effective 1 January 2010.

IERS Technical Note No. 35 (2009), 1-204

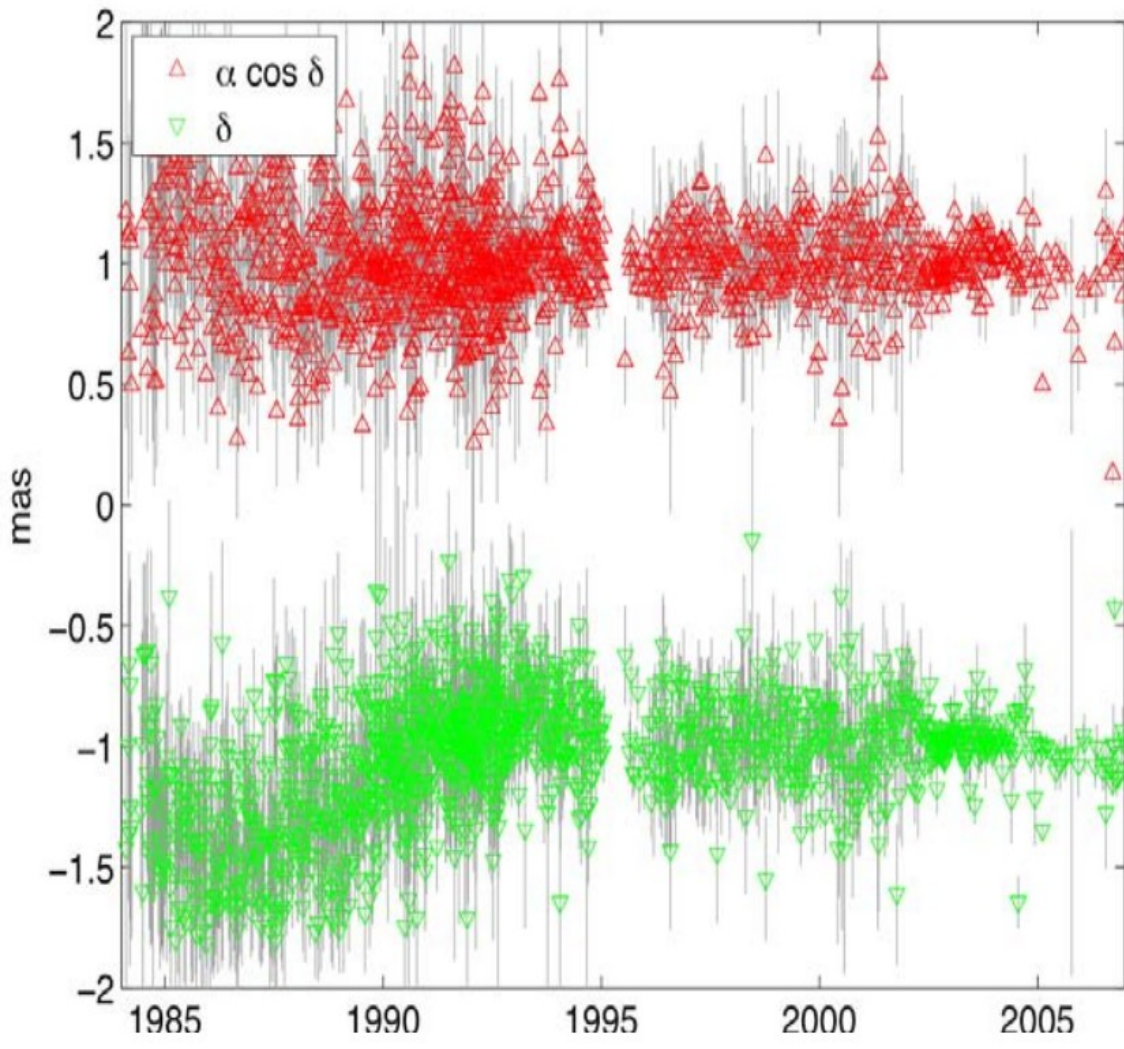
<http://www.iers.org/MainDisp.csl?pid=46-1100252>

Notes:

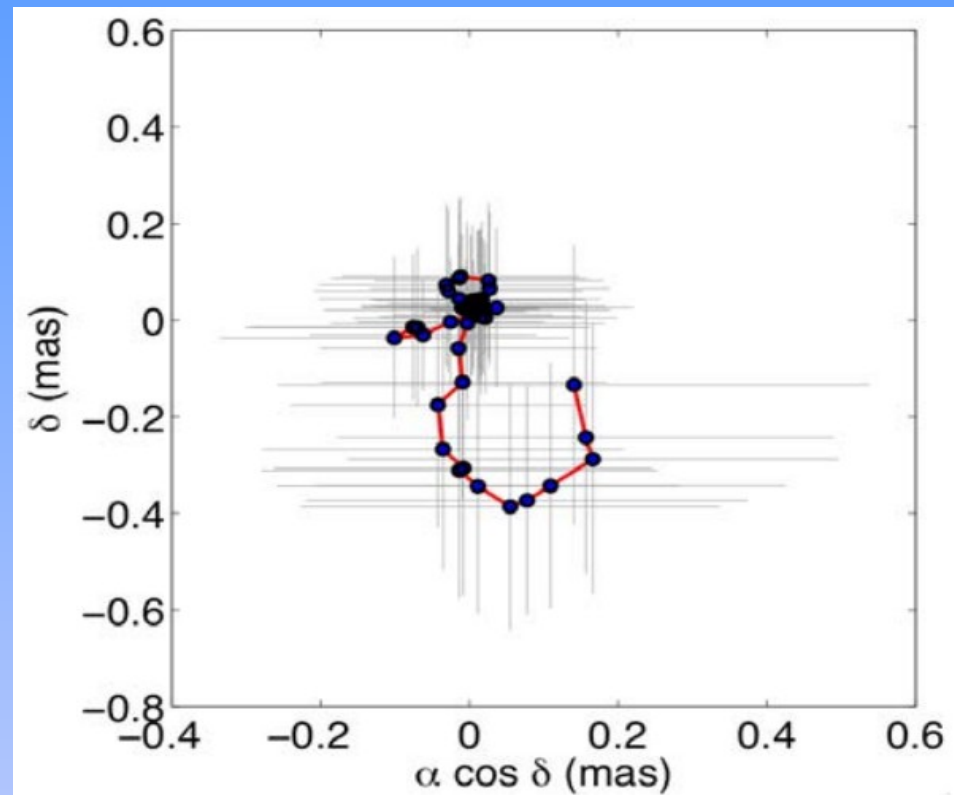
- (1) ICRF Designations, constructed from J2000.0 coordinates with the format
ICRF JHHMMSS.s+DDMMSS or ICRF JHHMMSS.s-DDMMSS
They follow the recommendations of the IAU Task Group on Designations.
- (2) IERS Designations, previously constructed from B1950 coordinates.
The complete format, including acronym and epoch in addition to the
coordinates, is
IERS BHHMM+Ddd or IERS BHHMM-DDd
- (3) D means defining sources, i.e. define the ICRF2 frame axes.
- (4) For the 39 special handling sources the correlation RA-DC is not available and set to 0.000

Coordinates of 1217 non UCS sources in ICRF2

ICRF Designation (1)	IERS Des. (2)	Inf. (3)	Right Ascension J2000.0			Declination J2000.0			Uncertainty		Corr. RA-DC (4)	Mean MJD of observation	First MJD	Last MJD	Nb sess.	Nb del.
			h	m	s	°	'	"	R.A. s	Dec. "						
ICRF J000108.6+191433	2358+189		00	01	08.62156690	19	14	33.8017390	0.00000490	0.0000984	0.080	53306.0	50085.5	54907.7	21	716
ICRF J000211.9-215309	2359-221		00	02	11.98262436	-21	53	09.8359742	0.00115400	0.0386714	0.971	54818.7	54818.7	54818.7	1	3
ICRF J000435.6-473619	0002-478	D	00	04	35.65550384	-47	36	19.6037899	0.00001359	0.0002139	0.383	52501.0	49330.5	54670.7	28	129
ICRF J000435.7+201942	0002+200		00	04	35.75829931	20	19	42.3174919	0.00001434	0.0002426	0.079	52600.4	52409.7	52983.7	3	102
ICRF J000557.1+382015	0003+380		00	05	57.17539168	38	20	15.1489409	0.00000488	0.0000621	-0.083	52010.2	48720.9	54718.7	26	1518
ICRF J000613.8-062335	0003-066		00	06	13.89288849	-06	23	35.3353162	0.00000277	0.0000437	-0.035	52342.2	47176.5	54889.8	1254	26713
ICRF J000800.3-233918	0005-239		00	08	00.36965673	-23	39	18.1511374	0.00002400	0.0007055	-0.650	50918.1	50632.3	54643.7	3	95
ICRF J001031.0+105829	0007+106	D	00	10	31.00590186	10	58	29.5043827	0.00000491	0.0000930	-0.187	53063.9	47288.7	54803.7	29	559
ICRF J001033.9+172418	0007+171		00	10	33.99063132	17	24	18.7613217	0.00000486	0.0000824	-0.098	51780.9	47931.6	54844.7	40	1242
ICRF J001052.5-415310	0008-421		00	10	52.51790008	-41	53	10.7781702	0.00019412	0.0043581	-0.068	50998.2	48162.4	52409.7	5	22
ICRF J001101.2-261233	0008-264	D	00	11	01.24673846	-26	12	33.3770171	0.00000660	0.0000936	-0.183	52407.5	47686.1	54768.6	45	592
ICRF J001135.2+082355	0009+081		00	11	35.26963063	08	23	55.5862723	0.00001305	0.0004120	-0.455	52574.8	49914.7	53609.2	2	100
ICRF J001331.1+405137	0010+405	D	00	13	31.13020334	40	51	37.1441040	0.00000482	0.0000683	-0.139	51619.2	48434.7	54713.7	22	1083
ICRF J001611.0-001512	0013-005	D	00	16	11.08855479	-00	15	12.4453413	0.00000435	0.0001005	-0.235	50403.0	47394.1	51492.8	67	716
ICRF J001708.4+813508	0014+813		00	17	08.47492105	01	35	08.1365288	0.00008598	0.0002624	0.000	50567.9	47023.3	54112.5	1185	61191
ICRF J001937.8+202145	0017+200		00	19	37.85450158	20	21	45.6446718	0.00000655	0.0001138	-0.040	51210.3	50085.5	53609.2	5	356
ICRF J001945.7+732730	0016+731	D	00	19	45.78641940	73	27	30.0174396	0.00000989	0.0000424	-0.050	49249.8	44343.6	54865.7	458	25038
ICRF J002232.4+060804	0019+058	D	00	22	32.44120914	06	08	04.2690807	0.00000439	0.0000956	-0.237	52705.8	47394.1	54880.7	42	800
ICRF J002427.3+243926	0021+243		00	24	27.33054544	24	39	26.2295755	0.00001415	0.0002517	-0.039	52670.8	52409.7	53307.8	11	115
ICRF J002442.9-420203	0022-423		00	24	42.98977943	-42	02	03.9479276	0.00006971	0.0013214	-0.582	51518.2	48162.4	53131.8	8	37
ICRF J002715.3+224158	0024+224		00	27	15.37153913	22	41	58.0688698	0.00004355	0.0006729	-0.137	50621.1	50085.5	54664.7	3	120
ICRF J002829.8+200026	0025+197		00	28	29.81848608	20	00	26.7443060	0.00001399	0.0003630	-0.143	50454.5	50085.5	54837.7	5	209
ICRF J002914.2+345632	0026+346		00	29	14.2246572	34	56	32.2471180	0.00003535	0.0004340	0.457	49505.8	47011.4	51386.3	14	234
ICRF J002945.8+055440	0027+056		00	29	45.89631066	05	54	40.7124201	0.00001584	0.0003807	-0.175	50645.2	49914.7	54643.7	2	123
ICRF J003525.3+613030	0032+612		00	35	25.31063011	61	30	30.7613057	0.00006099	0.0004981	0.307	53460.9	52620.7	53552.8	2	71
ICRF J003758.2+240711	0035+238		00	37	58.29982404	24	07	11.8699687	0.00016333	0.0046830	-0.479	54292.7	54292.7	54292.7	1	12
ICRF J003814.7-245902	0035-252		00	38	14.73550693	-24	59	02.2351862	0.00000815	0.0001397	-0.095	52498.1	50632.3	54907.7	7	301
ICRF J003820.5-020740	0035-024		00	38	20.52934827	-02	07	40.5476126	0.00001584	0.0004962	-0.410	54125.8	54125.8	54125.8	1	82
ICRF J003824.8+413706	0035+413	D	00	38	24.84359231	41	37	06.0003032	0.00000499	0.0000613	-0.035	52262.4	49422.9	54887.7	18	1024
ICRF J003939.6+141157	0037+139		00	39	39.61959335	14	11	57.5567419	0.00001465	0.0003107	-0.249	50925.2	50085.5	53193.7	6	195
ICRF J004007.8-590352	0037-593		00	40	07.84908888	-59	03	52.7640423	0.00006916	0.0007714	0.327	53594.7	52887.6	54457.4	5	30
ICRF J004204.5+232001	0039+230		00	42	04.54517179	23	20	01.0620234	0.00000425	0.0000798	-0.119	52211.0	48919.9	54795.7	21	1079
ICRF J004219.4+570836	0039+568		00	42	19.45169063	57	08	36.58060772	0.00002746	0.0002988	0.207	51249.7	49577.0	54664.7	2	146
ICRF J004847.1+315725	0046+316		00	48	47.14148006	31	57	25.0848725	0.00000468	0.0000875	-0.137	53102.3	50219.8	54739.7	23	813
ICRF J004943.2+023703	0047+023		00	49	43.23594851	02	37	03.7783255	0.00001326	0.0003898	-0.169	51750.4	49914.7	54872.7	5	185
ICRF J004959.4-573827	0047-579		00	49	59.47306878	-57	38	27.3399688	0.00001384	0.0001470	0.245	52043.3	47626.5	54706.7	39	189
ICRF J005041.3-092905	0048-097	D	00	50	41.31738756	-09	29	05.2102688	0.00000278	0.0000428	-0.030	51323.1	44773.8	54816.7	1802	41482
ICRF J005109.5-422633	0048-427	D	00	51	09.50182012	-42	26	33.2932480	0.00000932	0.0001177	0.013	53857.8	52306.7	54907.7	31	315
ICRF J005655.2+162513	0054+161		00	56	55.29432846	16	25	13.3409281	0.00000984	0.0001923	0.212	53385.7	50156.3	54852.7	6	130
ICRF J005748.8+302108	0055+300		00	57	48.88334932	30	21	08.8119505	0.00000590	0.0000921	-0.356	51950.0	50219.8	53178.7	22	869
ICRF J005805.0-053952	0055-059		00	58	05.06630952	-05	39	52.2778596	0.00000507	0.0001022	-0.066	53919.4	50576.2	54852.7	7	346
ICRF J005846.5-565911	0056-572		00	58	46.58117584	-56	59	11.4706965	0.00003993	0.0005795	0.358	50239.8	47626.5	52941.7	8	36



Positions by sessions



Radio source 1803+784

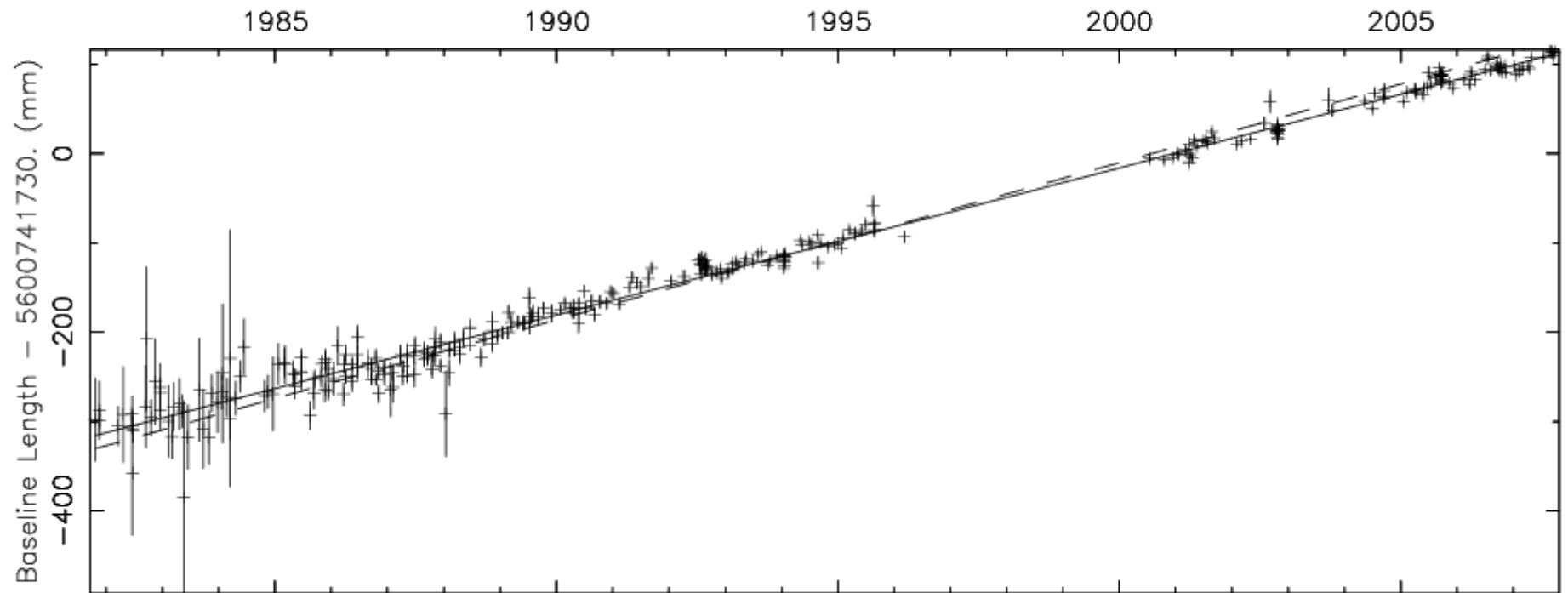
Semi-annual positions

Vector baseline plots for ONSALA60–WESTFORD

GSFC VLBI Solution 2007dnbe

Baseline length = 5600 kilometers

Number of sessions = 334



Observed Rate = 16.5 ± 0.1 mm/yr (scaled sig.)

Wrms of fit = 7.4 mm

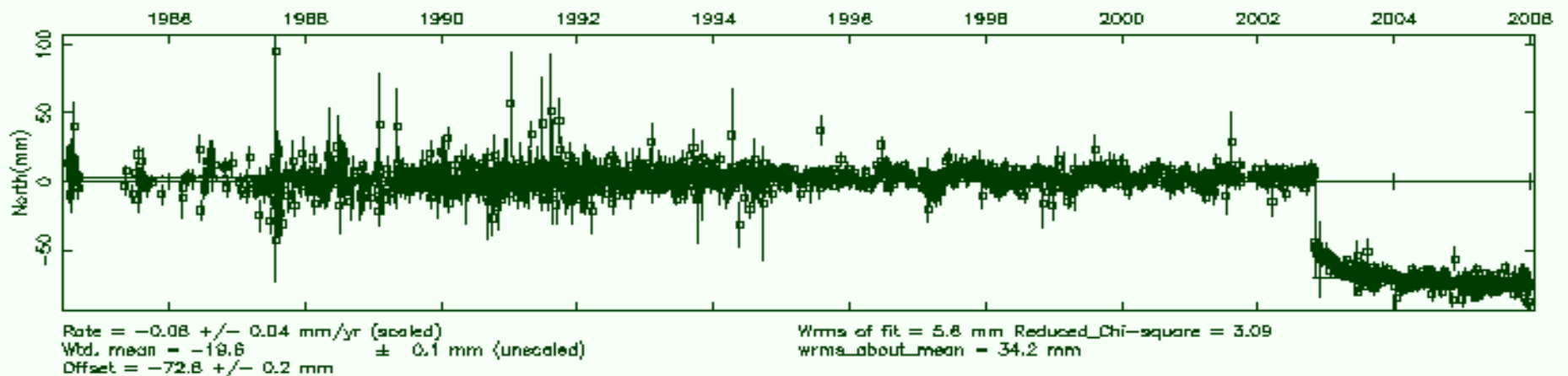
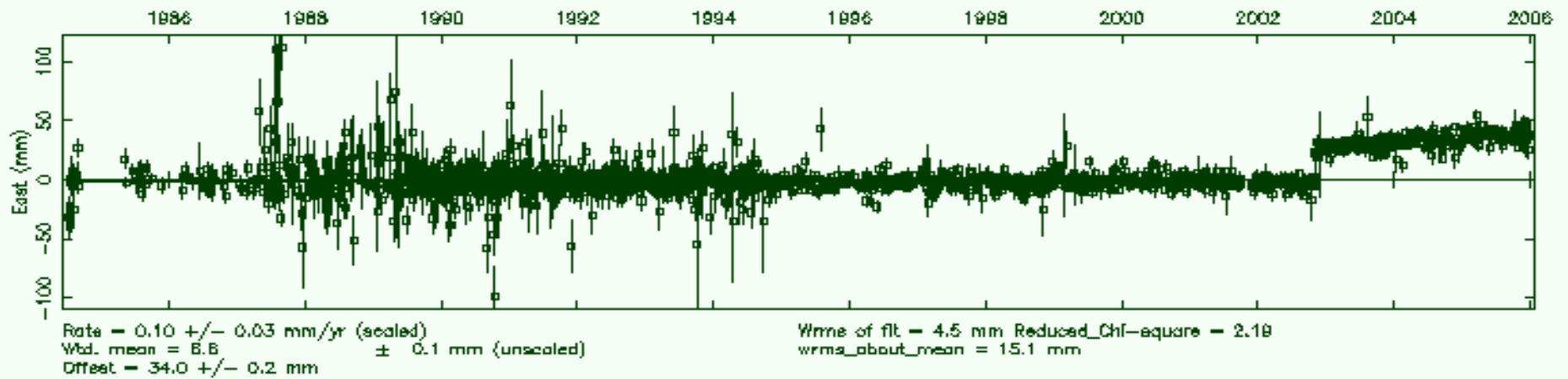
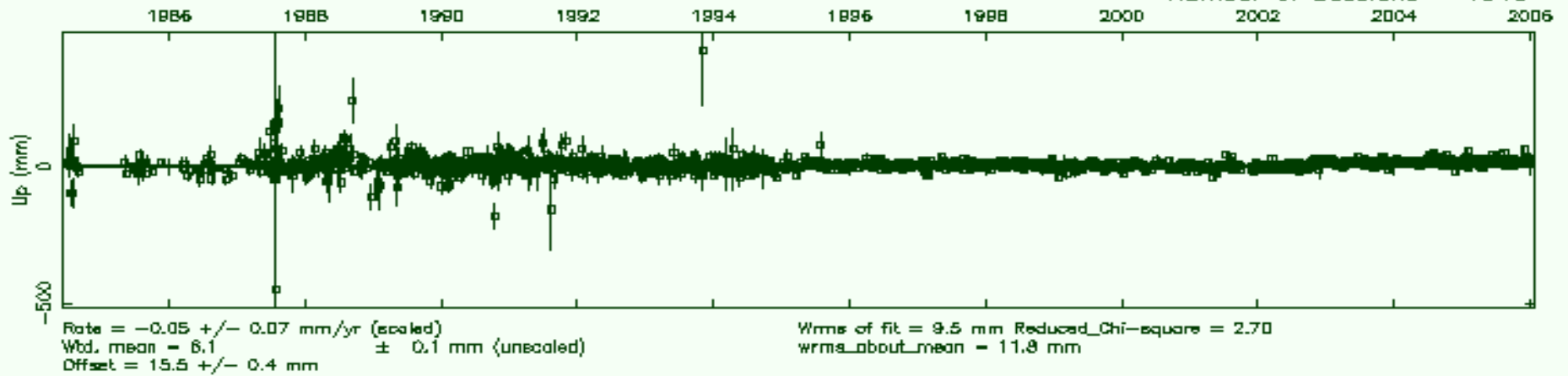
Reduced_Chi-square = 4.58

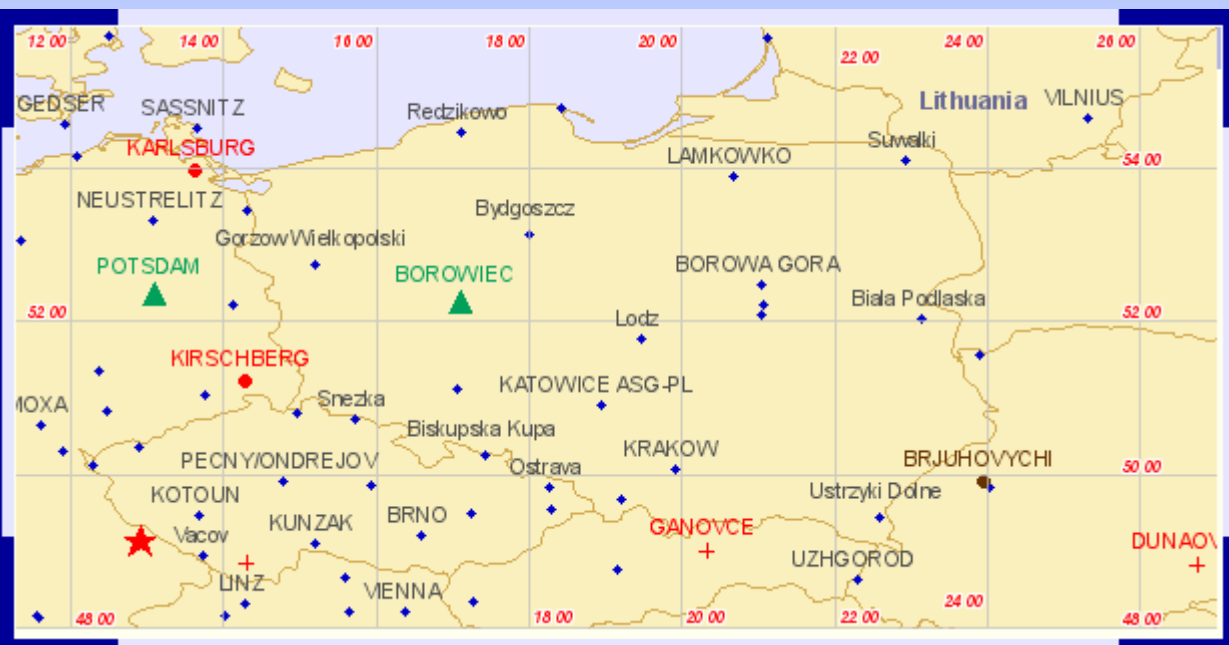
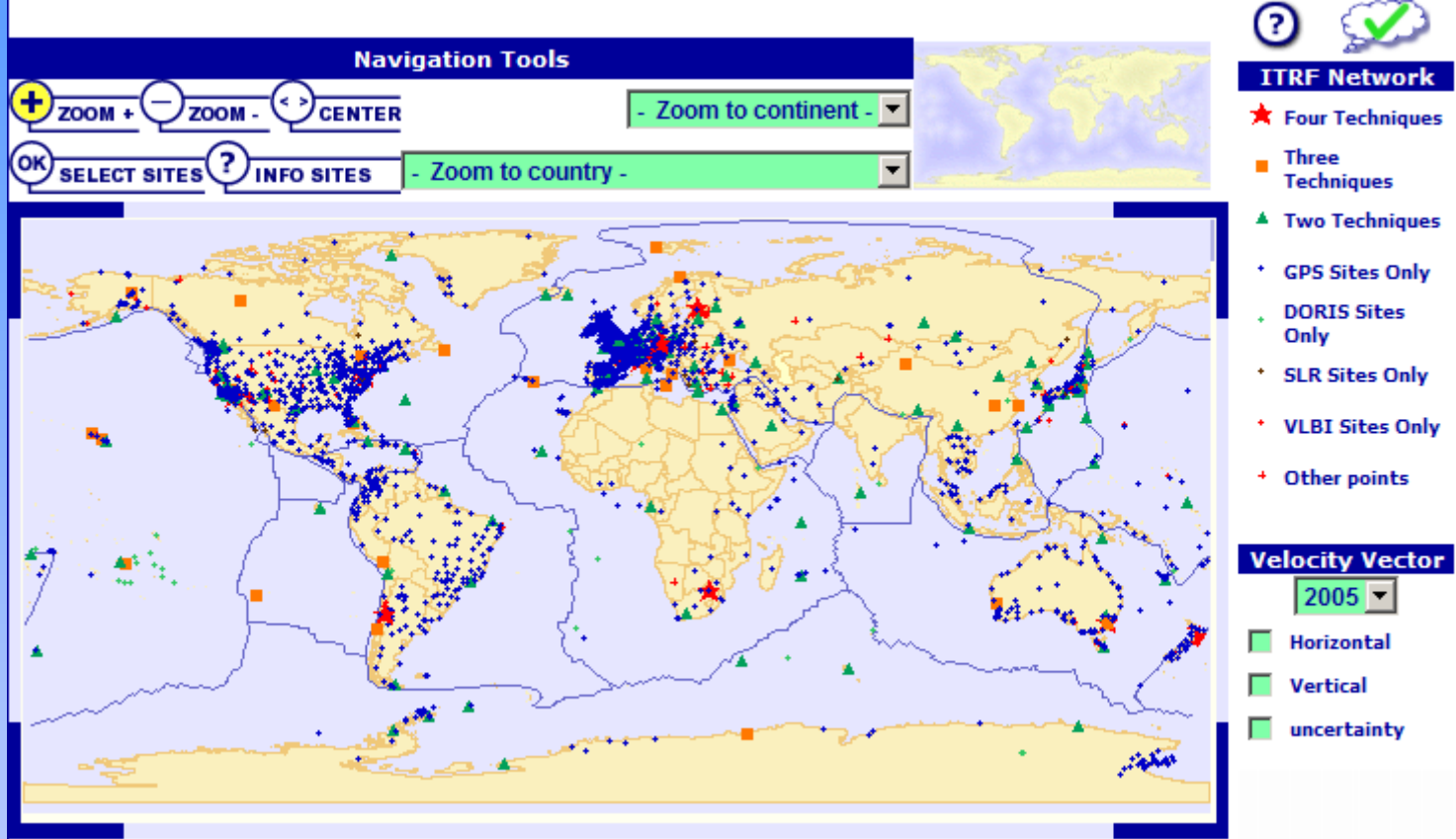
NUVEL model rate = 17.6 mm/yr

Weighted mean length = 5600741729.3 mm

Topocentric Site Repeatability Plots for GILCREEK
GSFC VLBI Solution 2007dnse

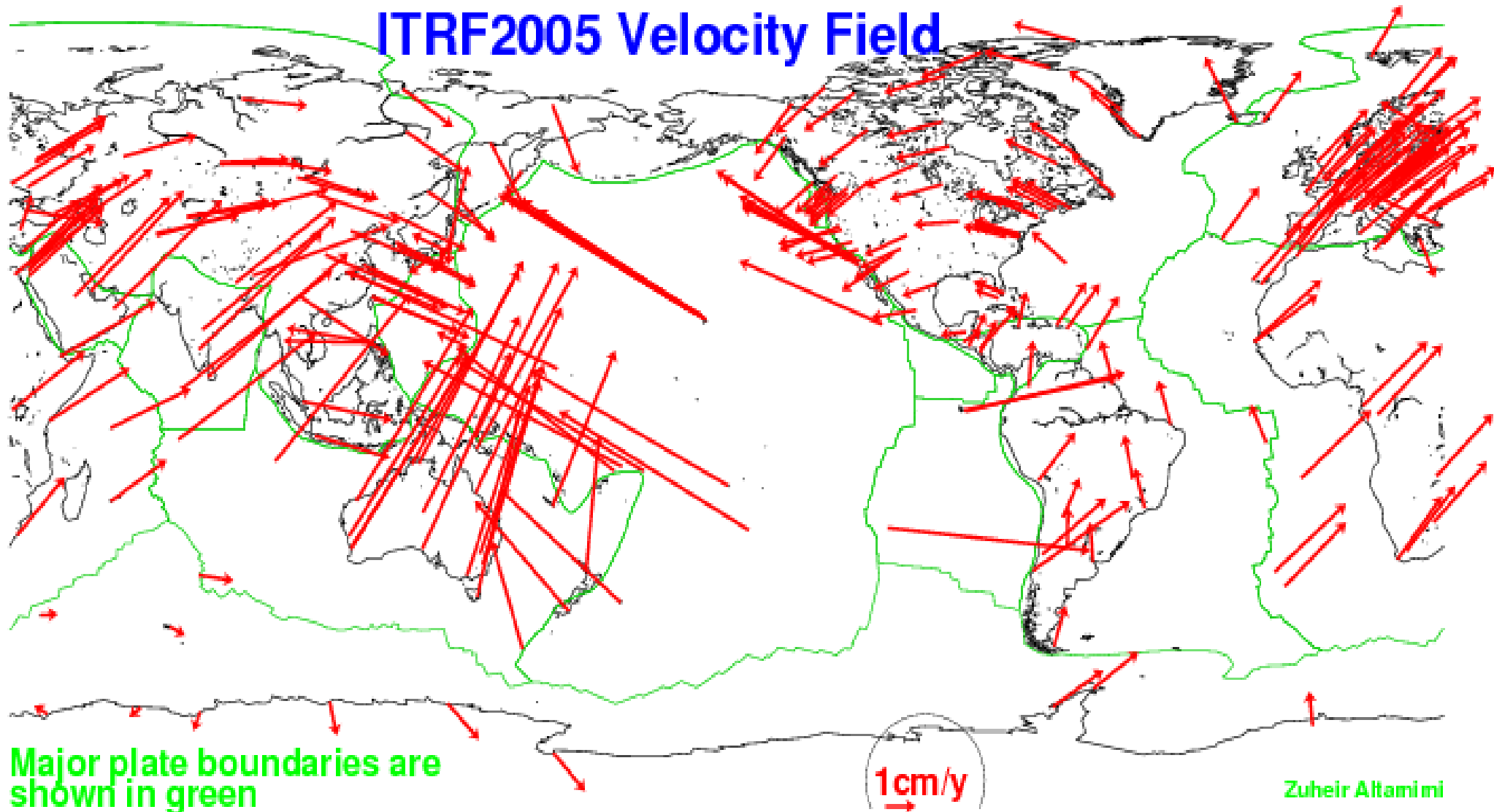
Number of Sessions = 1913



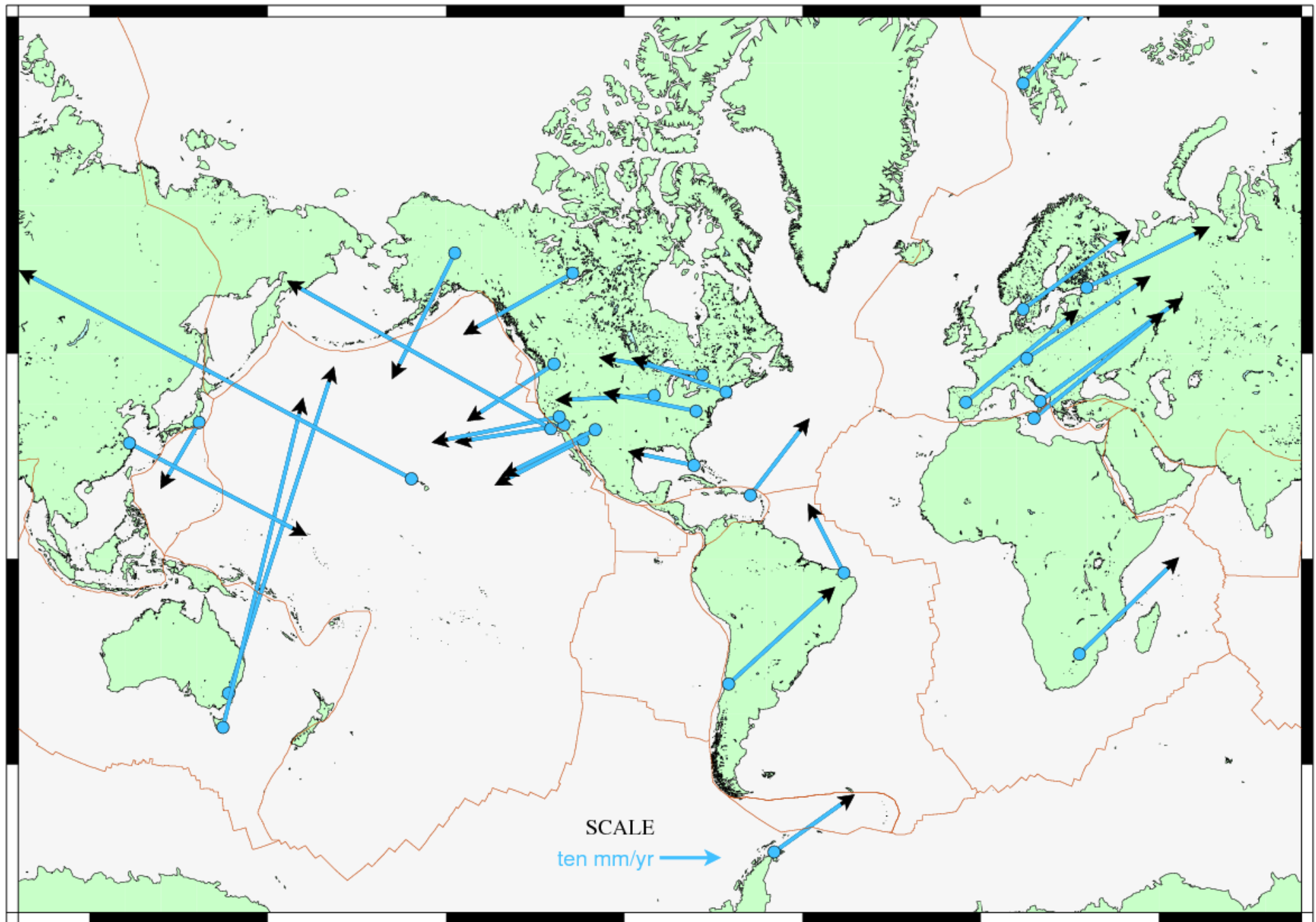


<http://itrf.ensg.ign.fr/GIS/index.php>

ITRF2005 Velocity Field

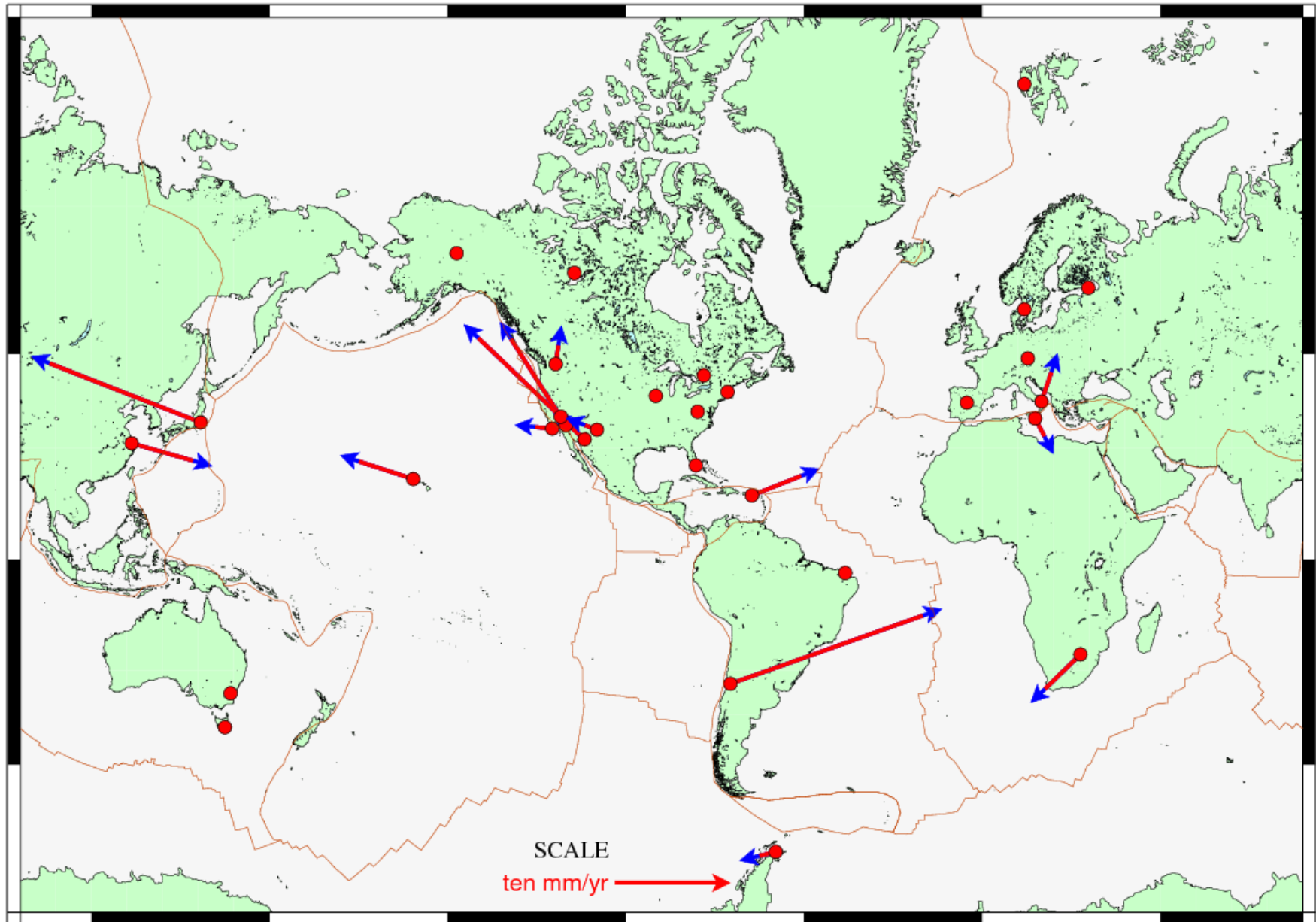


Selected VLBI Velocities



Goddard Space Flight Center VLBI solution KB 2007dn version 01
NUVEL1A-NNR reference frame.

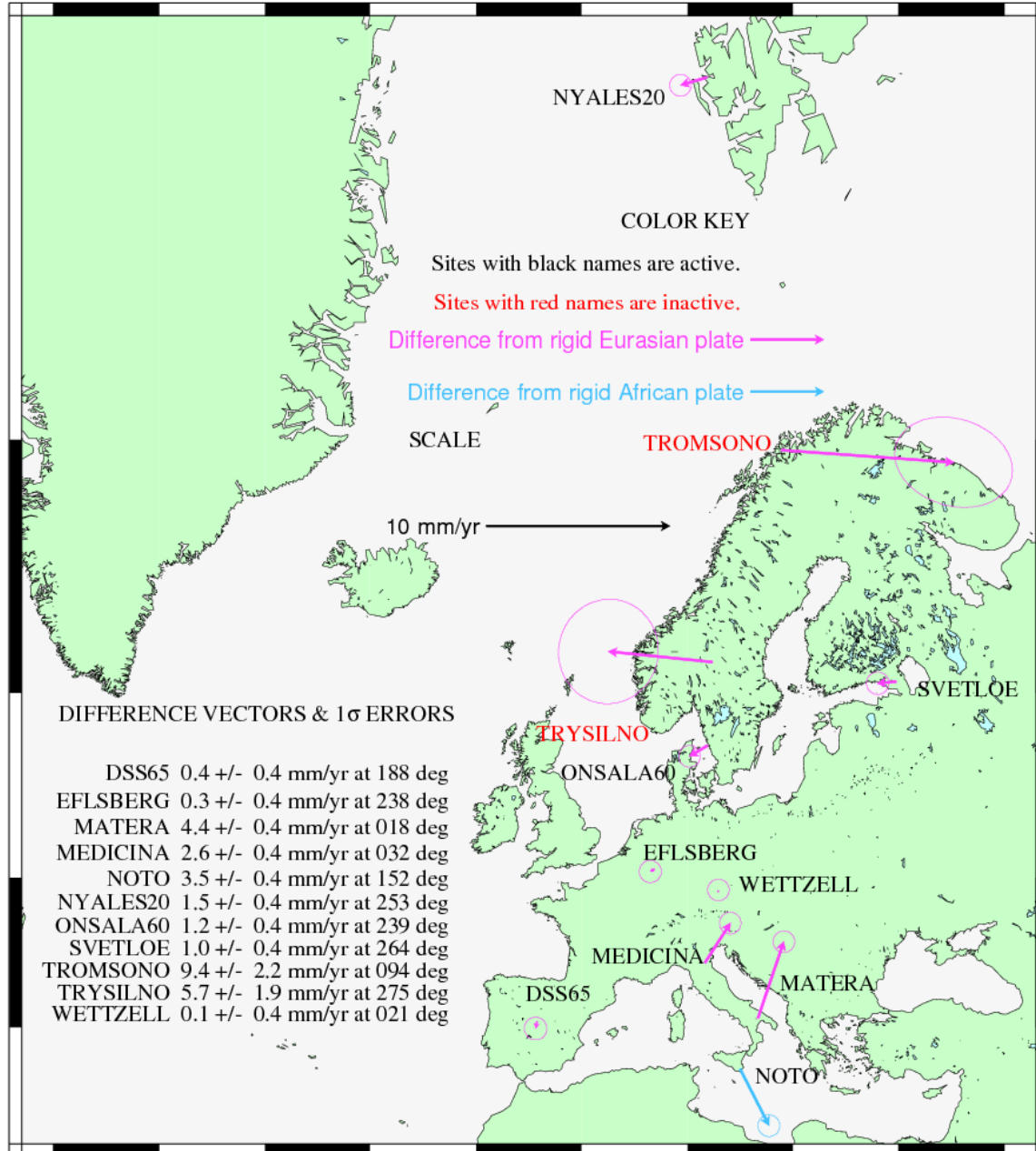
Differences between VLBI Velocities and Plate Model



Goddard Space Flight Center VLBI solution KB 2007dn version 01
Velocity residuals < 2 mm/yr are not displayed. NUVEL1A-NNR reference frame.

Europe

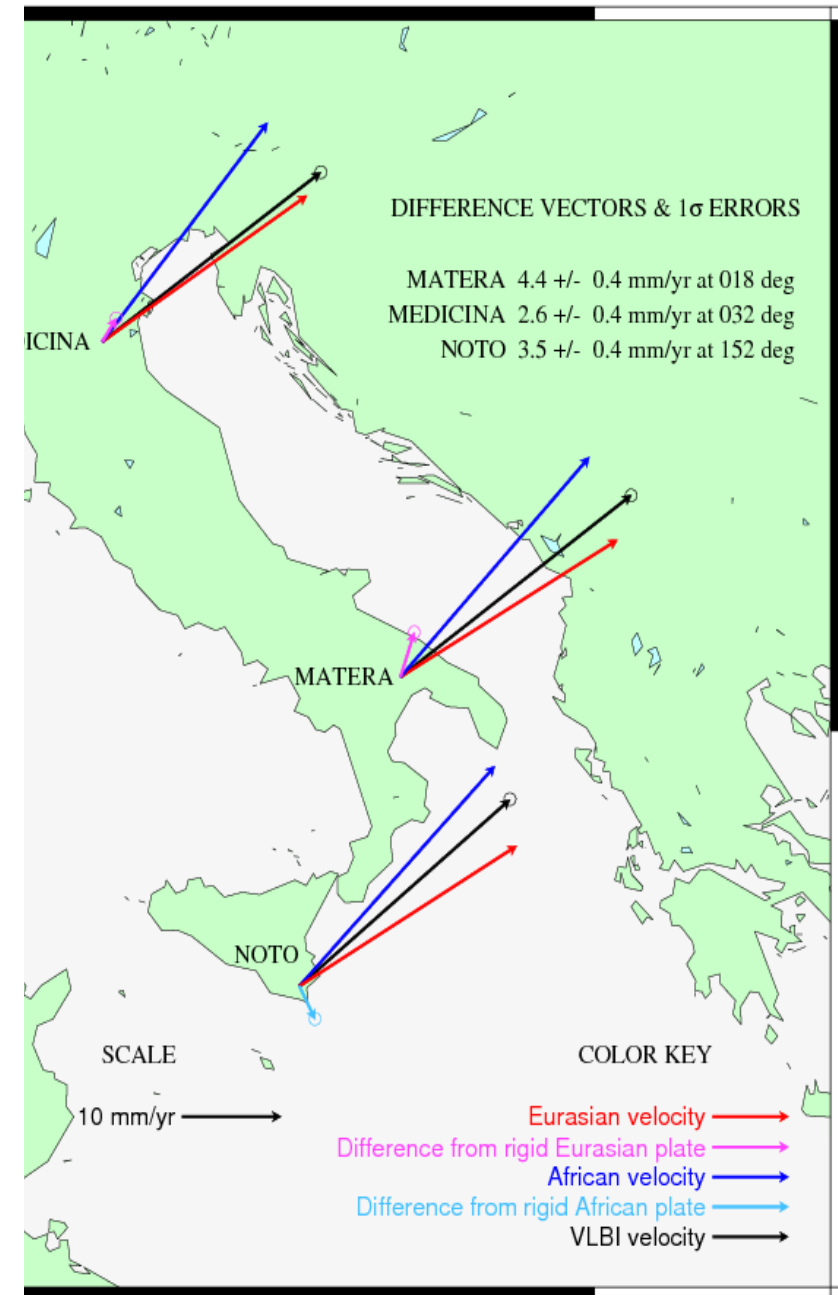
(Differences are from the rigid plate model)



Goddard Space Flight Center VLBI solution KB 2007dn version 01
 NUVEL1A-NNR reference frame. 1σ (realistic) error ellipses.

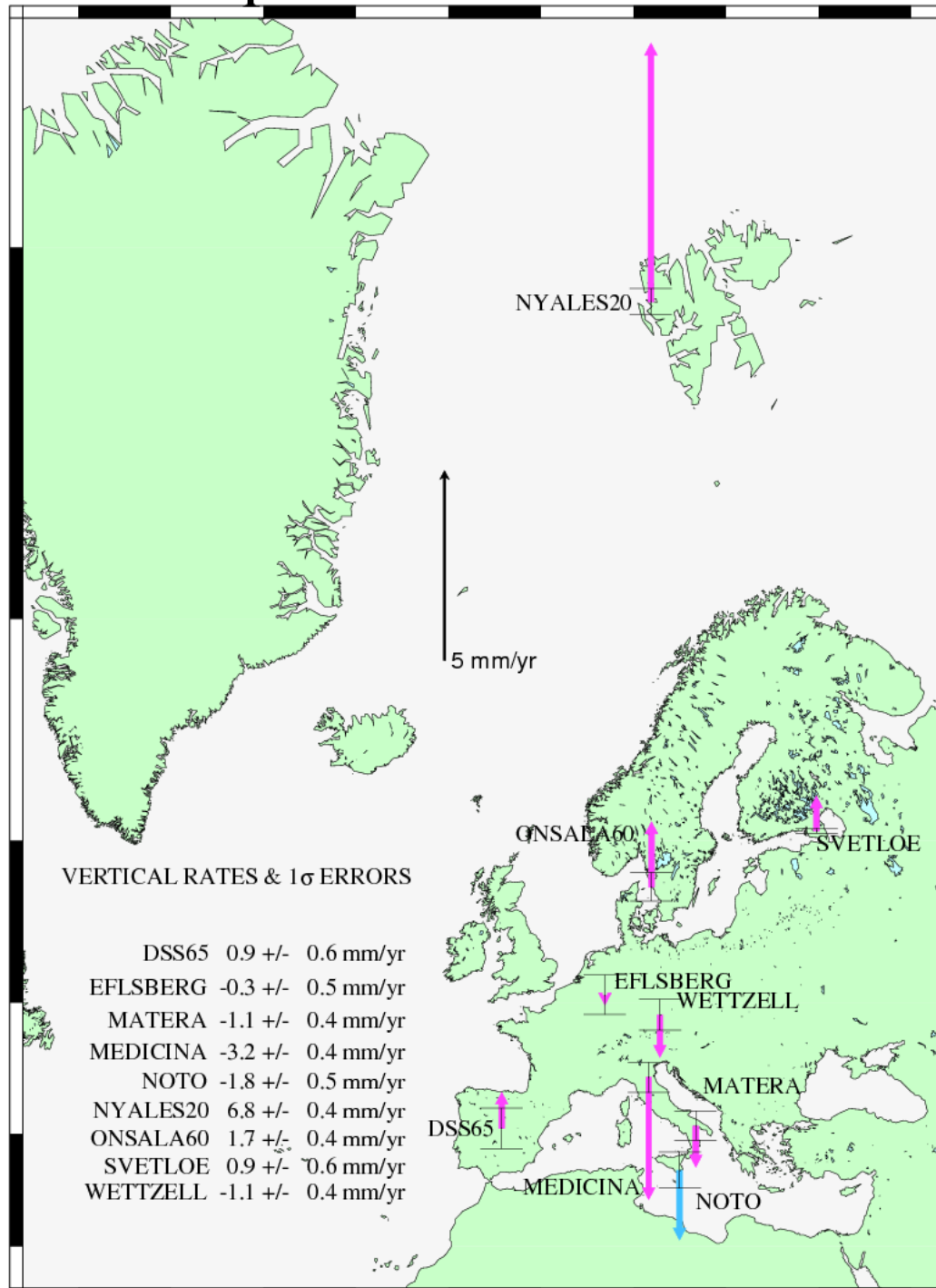
Italy

ing plates (Eurasian, African)



Goddard Space Flight Center VLBI solution KB 2007dn version 01
 NNR reference frame. 1σ (realistic) error ellipses.

European Vertical Motions

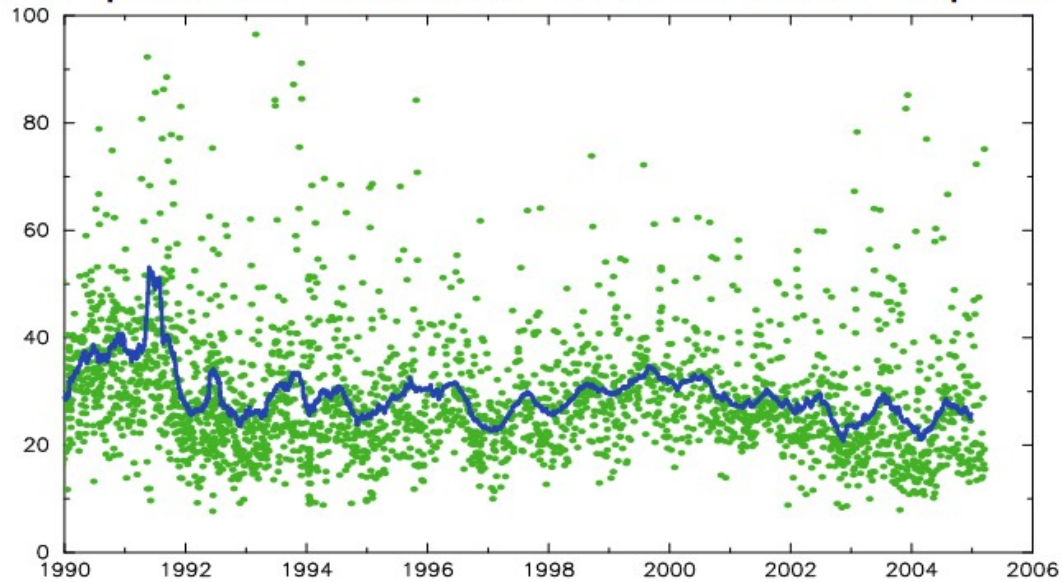


Goddard Space Flight Center VLBI solution KB 2007dn version 01
 1σ (realistic) error bars.

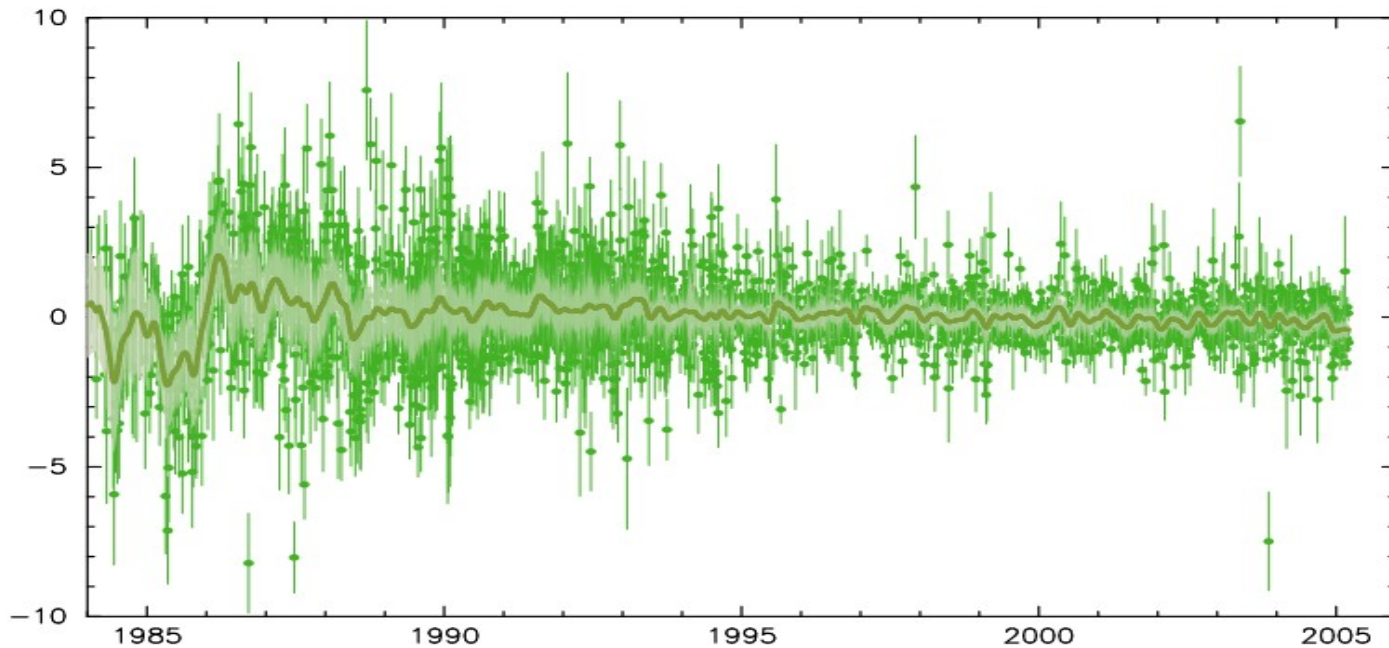
Were VLBI results improved in last 10 years?

Evolution of WRMS of post-fit residuals of individual experiments (on psec)

All data:



Differences: daily estimates of $\Delta\epsilon$ versus heo_05c (in nrad)

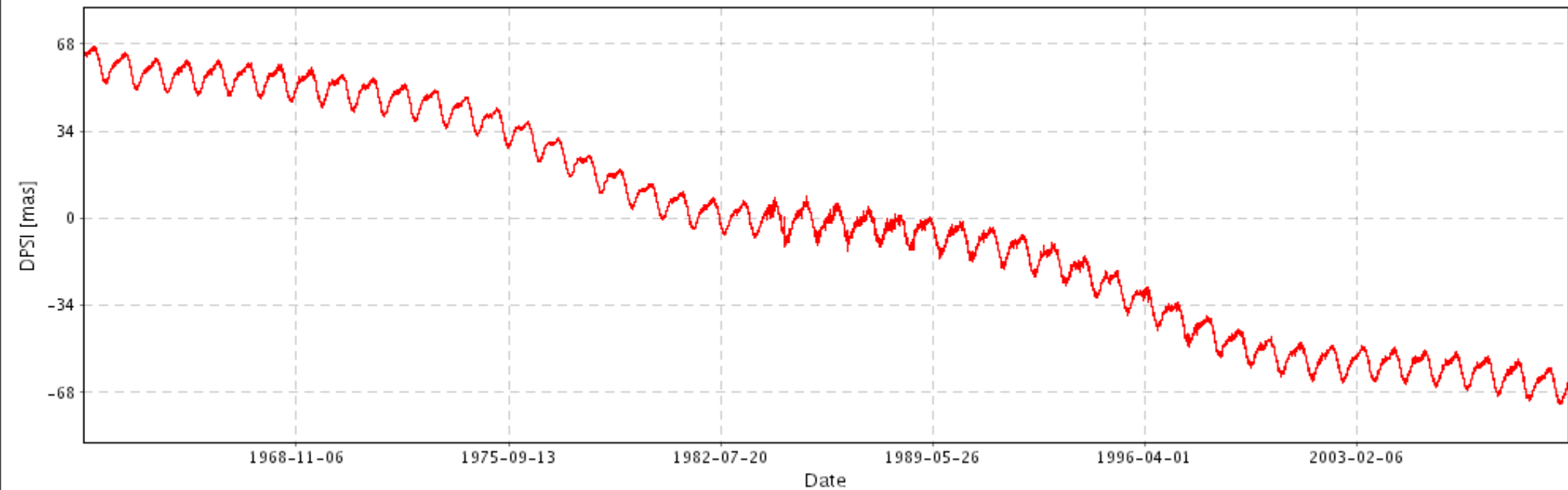


Leonid Petrov
GSFC (2007)

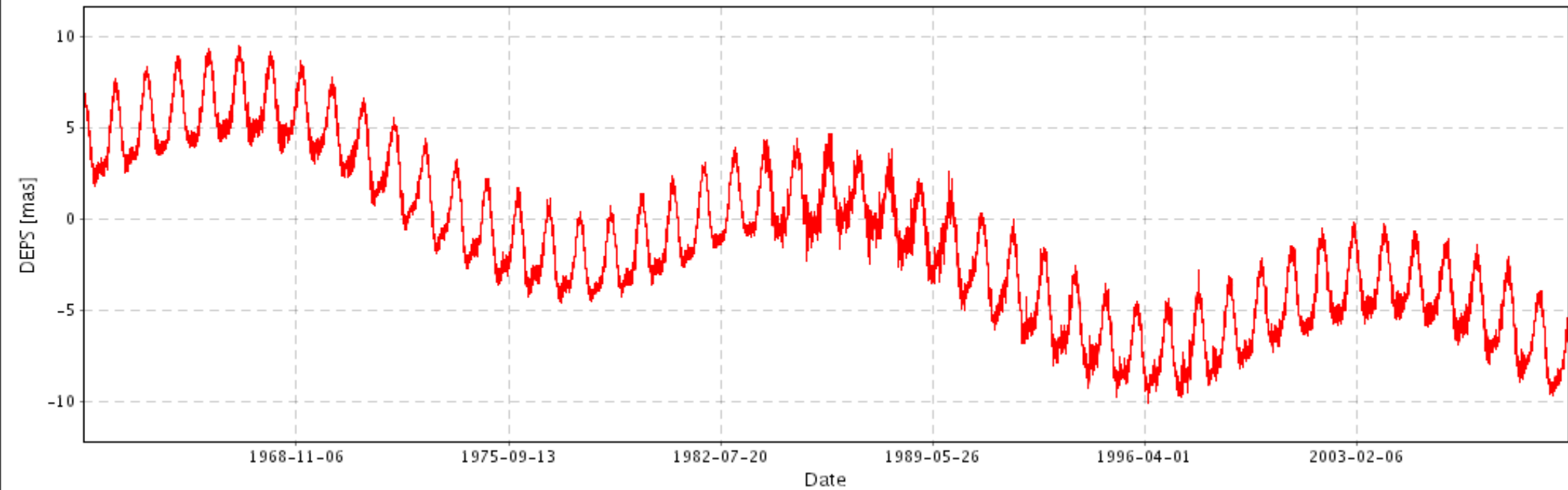
Summary of current IVS main products status and goals (WG2)

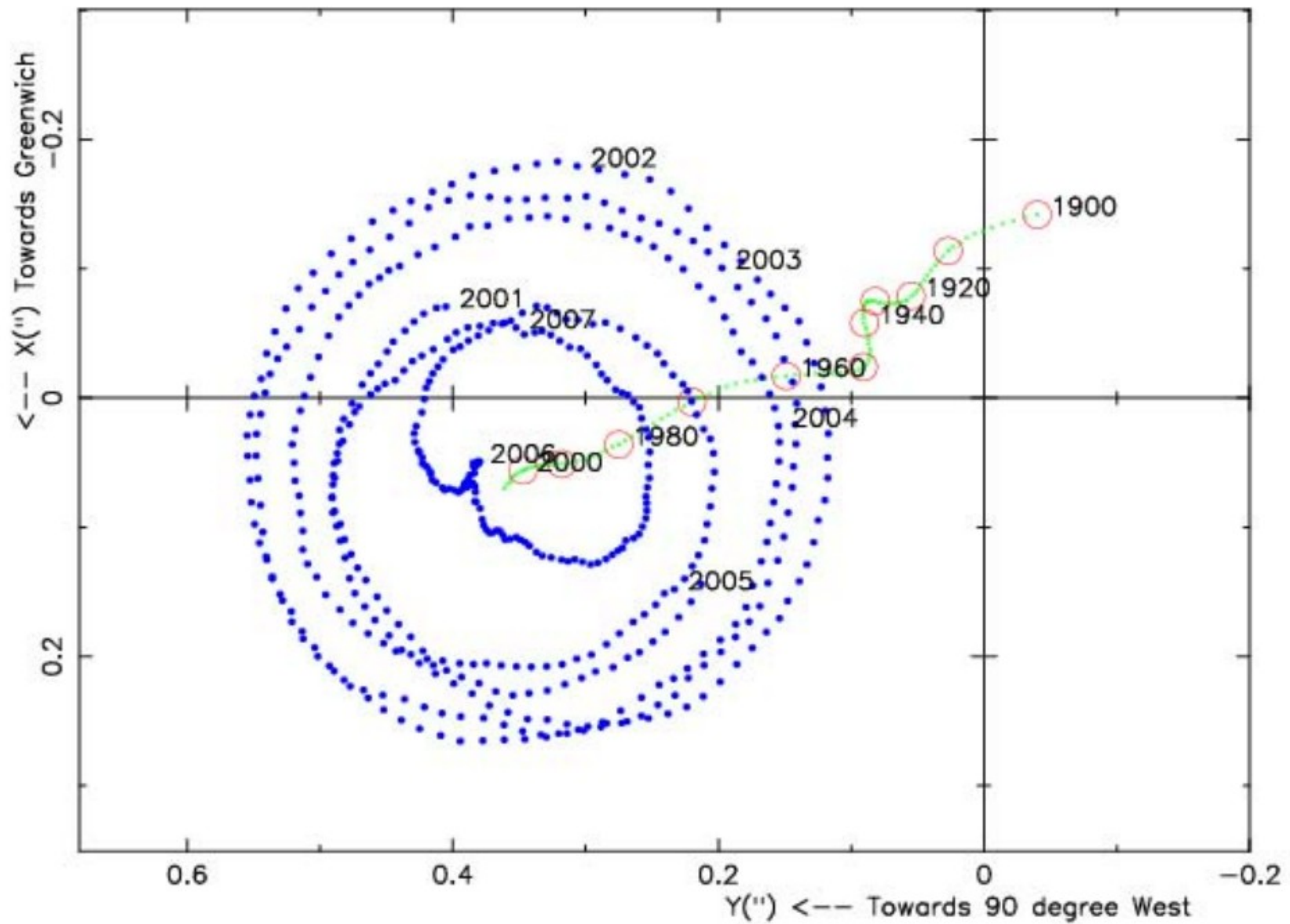
Products	Specification	Status 2002	Status 2006	Goals (2010)
Polar Motion (x_p, y_p)	accuracy product delivery resolution frequency of solution	$x_p \sim 100, y_p \sim 200 \mu\text{as}$ 1 – 4 weeks – 4 months 1 day 3 days/week	$x_p, y_p: 50 - 80 \mu\text{as}$ 8 – 12 days 1 day	25 μas 1 day 10 min – 1 h 7 days/week
UT1-UTC (DUT1)	accuracy product delivery resolution	5 – 20 μs 1 week 1 day	3 μs 3 – 4 days 1 day	2 μs 1 day 10 min
Celestial Pole ($d\epsilon; d\psi$)	accuracy product delivery resolution frequency of solution	100 – 400 μas 1 – 4 weeks – 4 months 1 day ~ 3 days/week	50 μas 3 – 4 days 1 day	25 μas 1 day 7 days/week
TRF (x, y, z)	accuracy	5 – 20 mm	5 mm	2 mm
CRF ($\alpha; \delta$)	accuracy frequency of solution product delivery	0.25 – 3 mas 1 year 3 – 6 months	0.25mas (improv. distribution) 1 year 3 months	0.25 mas improve. for more freq. Bands 1 month

DPSI / EOP 05 C04 / IAU1980



DEPS / EOP 05 C04 / IAU1980

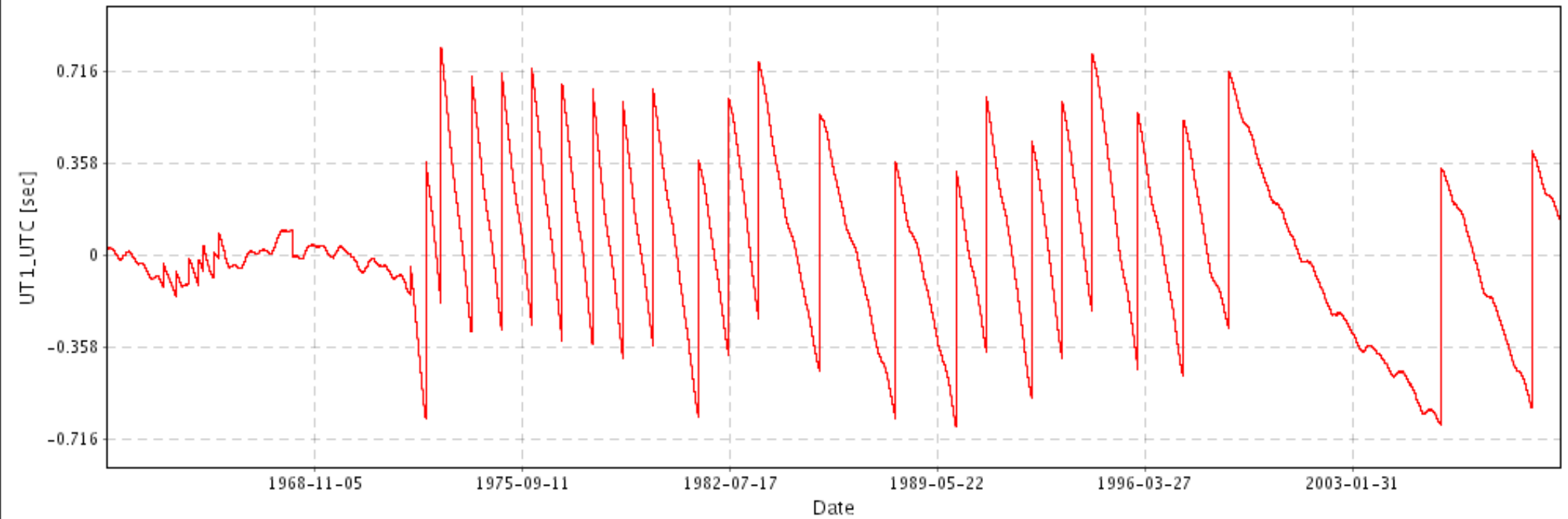




Mean polar motion (1900–2010) and IERS C04 polhody over 2001–2007

0.1" = 3.1 m

UT1_UTC / EOP 05 C04 / IAU1980



© IERS Plot-Tool 2009-12-03

INTERNATIONAL EARTH ROTATION AND REFERENCE SYSTEMS SERVICE (IERS)
SERVICE INTERNATIONAL DE LA ROTATION TERRESTRE ET DES SYSTEMES DE REFERENCE

SERVICE DE LA ROTATION TERRESTRE OBSERVATOIRE DE PARIS
61, Av. de l'Observatoire 75014 PARIS (France)
Tel. : 33 (0) 1 40 51 22 26
FAX : 33 (0) 1 40 51 22 91
Internet : services.iers@obspm.fr

Paris, 4 July 2009

Bulletin C 38

To authorities responsible
for the measurement and
distribution of time

INFORMATION ON UTC - TAI

**NO positive leap second will be introduced at the end of December 2009.
The difference between Coordinated Universal Time UTC and
the International Atomic Time TAI is :**

from 2009 January 1, 0h UTC, until further notice : UTC-TAI = -34 s

Leap seconds can be introduced in UTC at the end of the months of December or June, depending on the evolution of UT1-TAI. Bulletin C is mailed every six months, either to announce a time step in UTC, or to confirm that there will be no time step at the next possible date.

Daniel GAMBIS
Director Earth Orientation Center of IERS
Observatoire de Paris, France

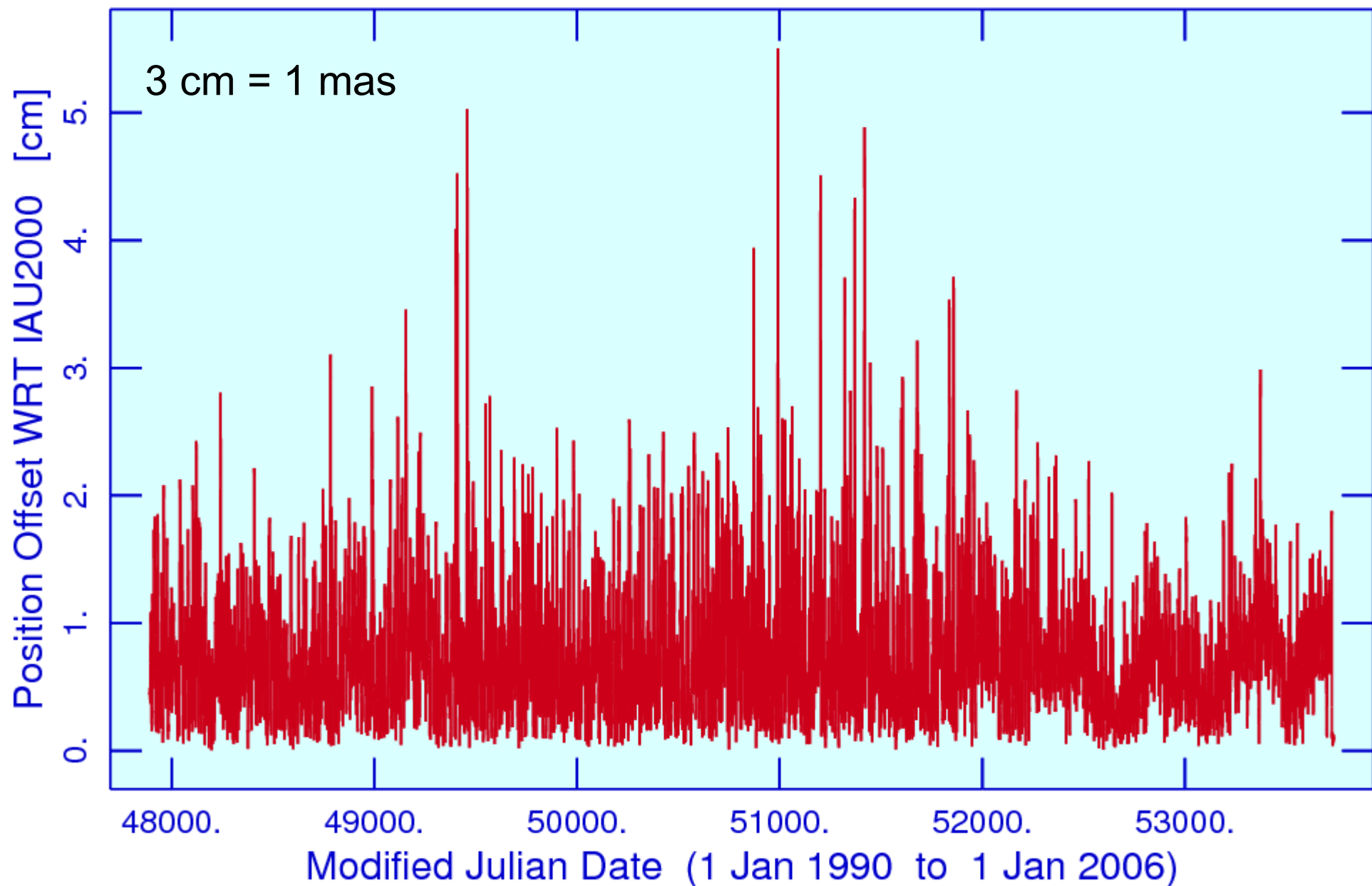
INTERNATIONAL EARTH ROTATION AND REFERENCE SYSTEMS SERVICE
 EARTH ORIENTATION PARAMETERS
 EOP (IERS) 05 C04

FORMAT(2X,A4,I3,2X,I5,2F9.6,F10.7,2X,F10.7,2X,2F9.5)

Date	MJD	x	y	UT1-UTC	LOD	dPsi	dEpsilon
(0h UTC)		"	"	S	S	"	"

YEAR ==> 2009

JAN	1	54832	-0.017015	0.146239	0.4071571	0.0010652	-0.06204	-0.00406
JAN	2	54833	-0.020427	0.147557	0.4059743	0.0012254	-0.06205	-0.00405
JAN	3	54834	-0.023271	0.149075	0.4046727	0.0013034	-0.06207	-0.00407
JAN	4	54835	-0.025730	0.150747	0.4033484	0.0013056	-0.06213	-0.00416
JAN	5	54836	-0.029031	0.152761	0.4020737	0.0012186	-0.06235	-0.00425
JAN	6	54837	-0.033382	0.154569	0.4009134	0.0010519	-0.06279	-0.00418
JAN	7	54838	-0.037543	0.156256	0.3999417	0.0008139	-0.06338	-0.00401
JAN	8	54839	-0.041695	0.158084	0.3992281	0.0005951	-0.06382	-0.00397
JAN	9	54840	-0.045900	0.159694	0.3986841	0.0005417	-0.06373	-0.00418
JAN	10	54841	-0.049566	0.161235	0.3981287	0.0006182	-0.06307	-0.00440
JAN	11	54842	-0.053086	0.162767	0.3974553	0.0008102	-0.06232	-0.00439
JAN	12	54843	-0.056504	0.164437	0.3965109	0.0011084	-0.06195	-0.00426
JAN	13	54844	-0.059603	0.166143	0.3952847	0.0013483	-0.06187	-0.00428
JAN	14	54845	-0.062424	0.167713	0.3938421	0.0014988	-0.06177	-0.00447
JAN	15	54846	-0.065337	0.169328	0.3923319	0.0015110	-0.06182	-0.00455



Absolute difference between the Explorer location referred to the geocentric ICRF computed with two packages: the Top2Bary and T2C2kA, the latter incorporating full precision software based on the 1997–2000 IAU astronomical reference systems, time scales, and Earth rotation models.

Hipparcos Celestial Reference Frame

Launched in August 1989 Hipparcos successfully observed the celestial sphere for 3.5 years before operations ceased in March 1993.

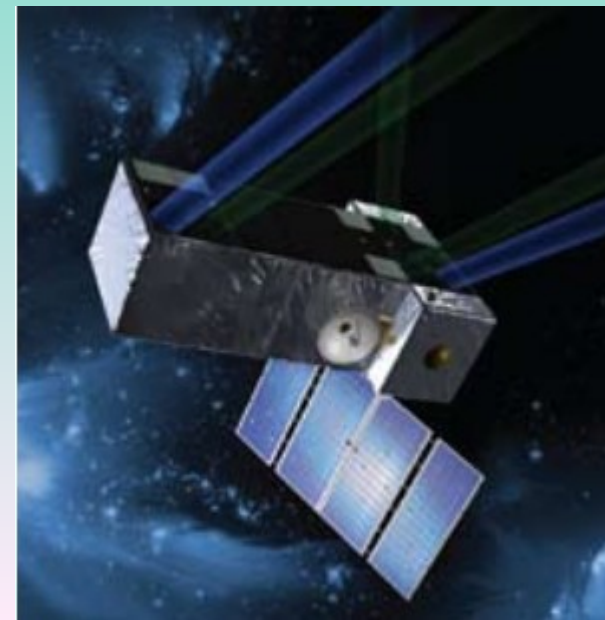
The Hipparcos catalogue contains 118,218 stars. The positional accuracies of 1 to 3 mas at epoch 1991.25 are unsurpassed in the optical. Proper motion accuracies, of around 1 to 2 mas/yr, remain state of the art. **Thus typical positional errors at a 2005 epoch are around 15 mas.**

The **Tycho 2 Catalogue**, completed in 2000, contains 2,539,913 stars. Positional accuracies range from about 10 to 100 mas, depending on magnitude. Proper motion accuracies are from 1 to 3 mas.

Over 10 years after the successful Hipparcos mission a first attempt was made to improve upon the original link between the HCRF and the extragalactic ICRF (Bobylev et al., 2004). The **possible error** in the alignment between the 2 systems increases with time, approaching about **3 mas** estimated standard error per axis at the 2005 epoch.

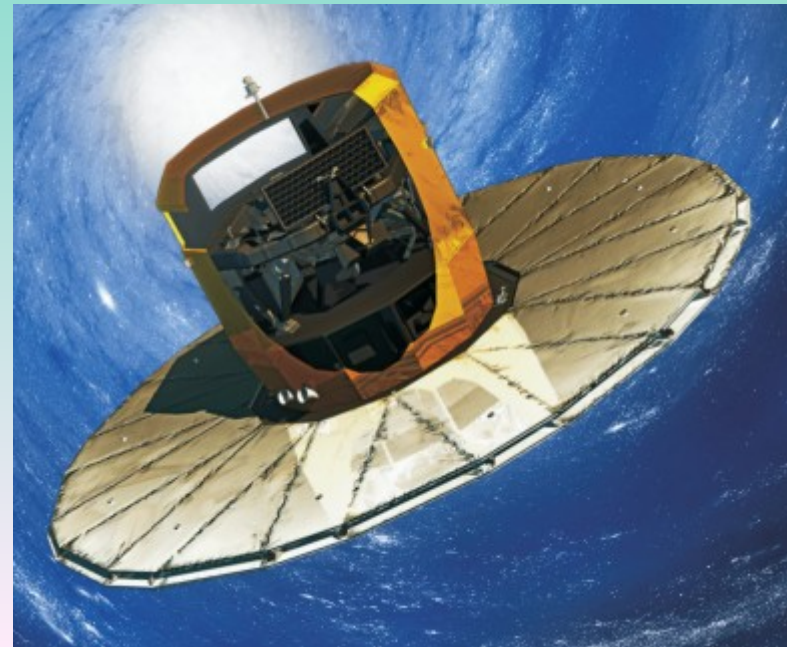
SIM-Planet Quest

- **Synopsis:** SIM Planet Quest is a space-based optical interferometer operating in a near Earth-trailing orbit
- **Acronym:** Space Interferometer Mission
- **Funding Agency:** NASA
- **Launch:** 2010 (plan). Five year baseline mission, potential ten year extended mission
- **ConOps:** SIM Planet Quest is a pointed mission with predefined targets
- **Number of Objects:** about 10,000 stars (1,300 grid stars)
- **Magnitude Range:** brighter than (a limiting magnitude of) about 20th
- **Astrometric Accuracy:** 4 microarcseconds wide angle, 1 microarcsec. narrow angle
- **Reference Frame:** Should SIM achieve 4 microarcseconds wide angle astrometric accuracy, the resultant grid will form the basis of the most accurate reference frame ever produced, easily exceeding the accuracy of the current radio-based ICRF. SIM will also be capable of observing a fair number of extragalactic sources. Detailed plans are currently being developed with regard to SIM observations of the extragalactic frame sources.
- **Additional Information:** SIM Planet quest is currently in mission development Phase B (Preliminary Design phase).



Gaia

- **Synopsis:** Gaia is a funded space astrometry mission intended to launch in 2010-2012 Operating at L2, Gaia consists of three instruments which provide astrometric, photometric, and spectroscopic data
- **Funding Agency:** ESA
- **Launch:** before 2012 (planned). Five year operation phase
- **ConOps:** Continuous scanning. Two optically combined fields of view
- **Number of Objects:** 10^9
- **Magnitude Range:** 7-20th magnitude
- **Astrometric Accuracy:** 15-20 microarcseconds @ 15th m_v
- **Reference Frame:** The stated accuracy goal of Gaia is somewhat less than that of SIM-PlanetQuest. What Gaia loses in accuracy, however, is easily overcompensated in the number of mission objects, of order 10^5 more than SIM-PlanetQuest. Gaia will also detect and measure the positions of about 400,000 QSOs, enabling an extremely rigid attachment of the impressively dense Gaia stellar frame to the extragalactic frame
- **Additional Information:** In addition to astrometry, Gaia will provide 12 band millimagnitude photometry, radial velocity data for brighter stars to an accuracy of a few km/s and spectrophotometry in the visible and near-IR to m_v 17.5

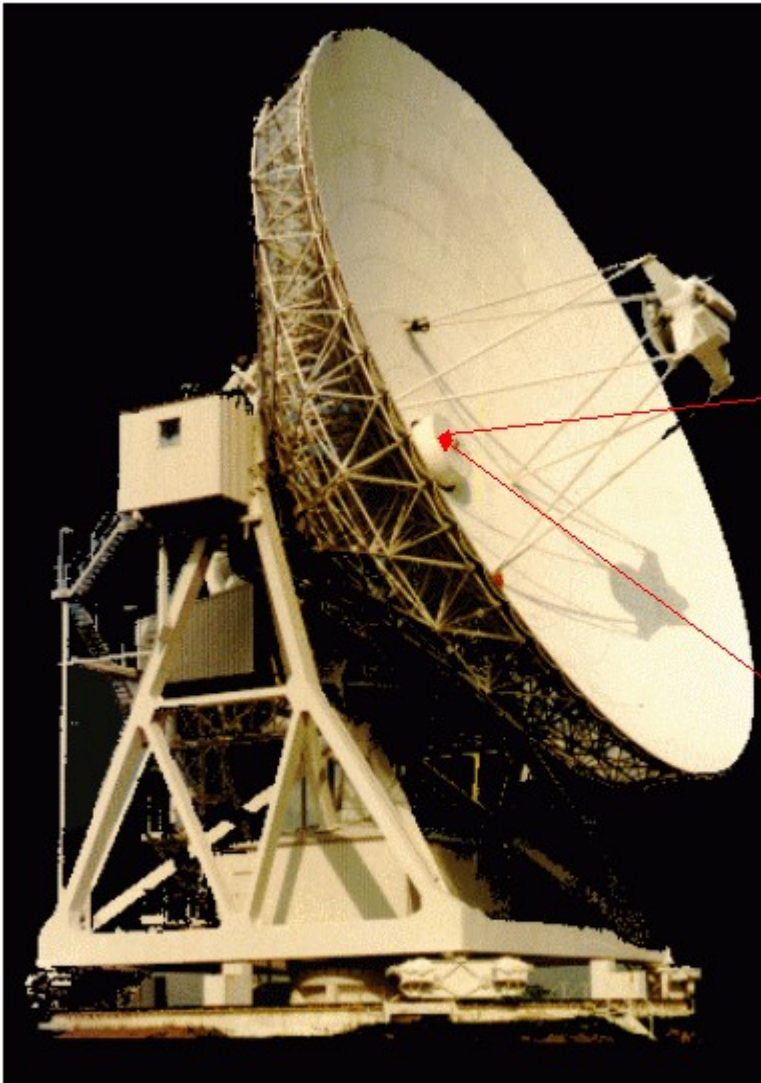


Radioteleskop 32- i 15-metrowy w Piwnicach k. Torunia

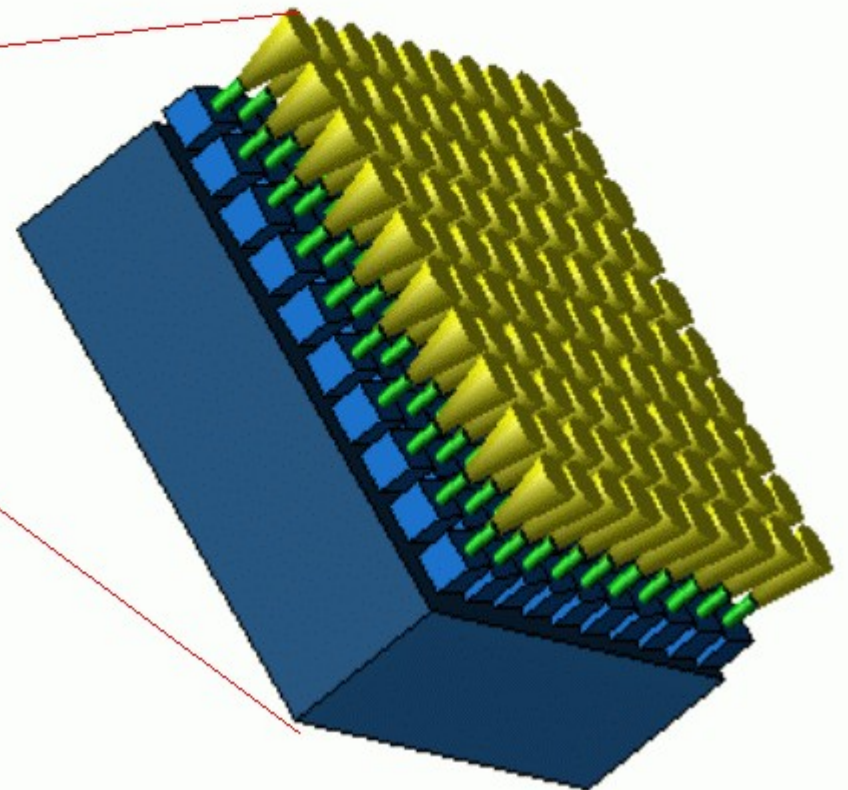




Oświetlacze w ognisku wtórnym RT32



OCRA One Centimetre Receiver Array



OCRA (One Centimetre Receiver Array), scientific papers

- "OCRA: a One-Centimetre Receiver Array", Proc. SPIE, 4015
- "30 GHz flux density measurements of the Caltech-Jodrell flat-spectrum sources with OCRA-p", A&A, 474, 1093L
- "Preliminary Sunyaev Zel'dovich Observations of Galaxy Clusters with OCRA-p", MNRAS, 378, pp 673-680
- "Survey of Planetary Nebulae at 30 GHz with OCRA-p", A&A, 498, 463
- "30 GHz observations of sources in the VSA fields", MNRAS (Submitted)

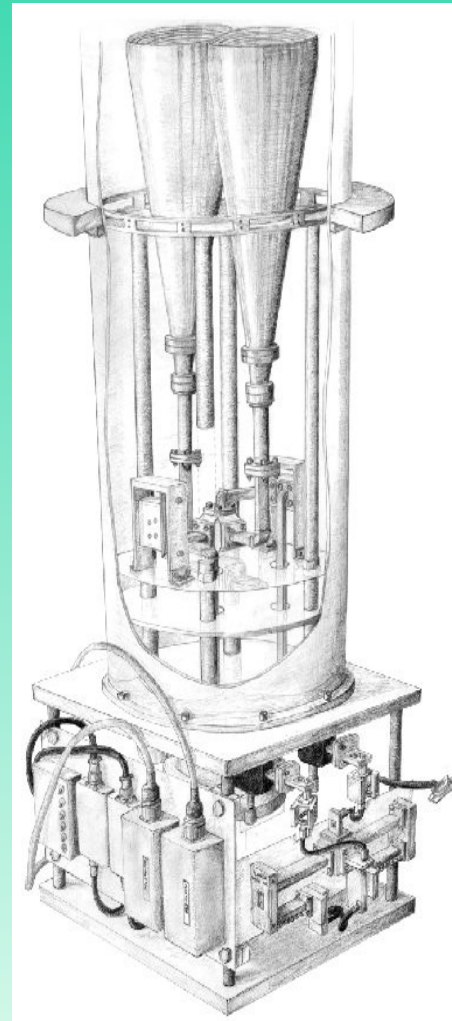
MANCHESTER
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The OCRA project aims to construct a one hundred beam receiver system, operating in a frequency band centred on 30 GHz

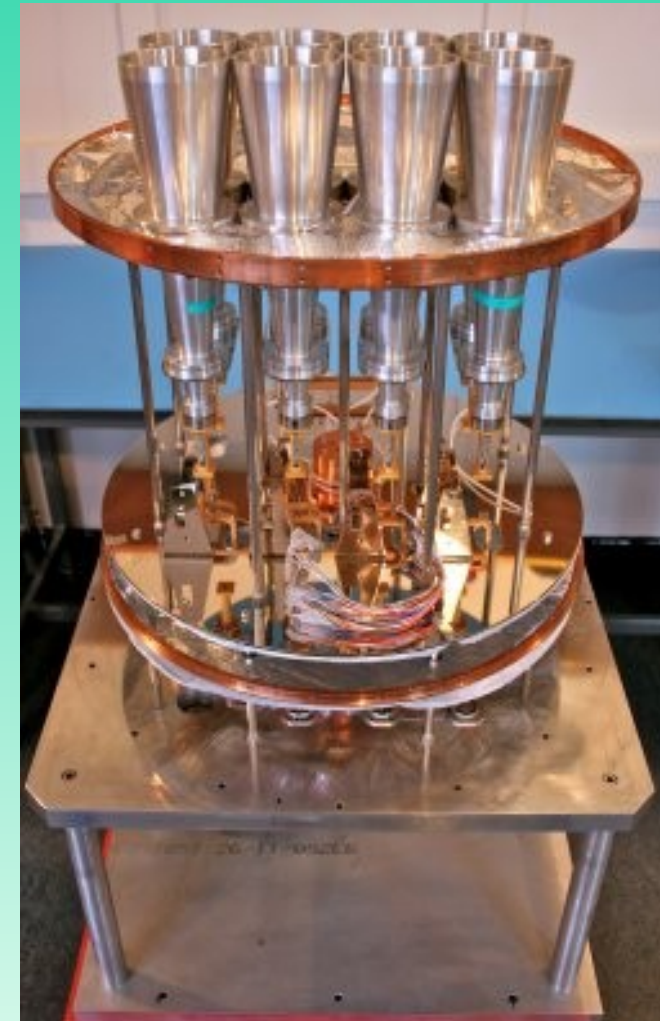
OCRA-F is currently being assembled and is expected to begin observing at the start of 2010, with an upgrade to 16 beams around 2012. OCRA-F will be used to do small scale blind surveys for point sources and the Sunyaev-Zel'dovich effect, and will also be able to create maps of extended emission.

<http://www.jb.man.ac.uk/research/ocra/>

OCRA-p



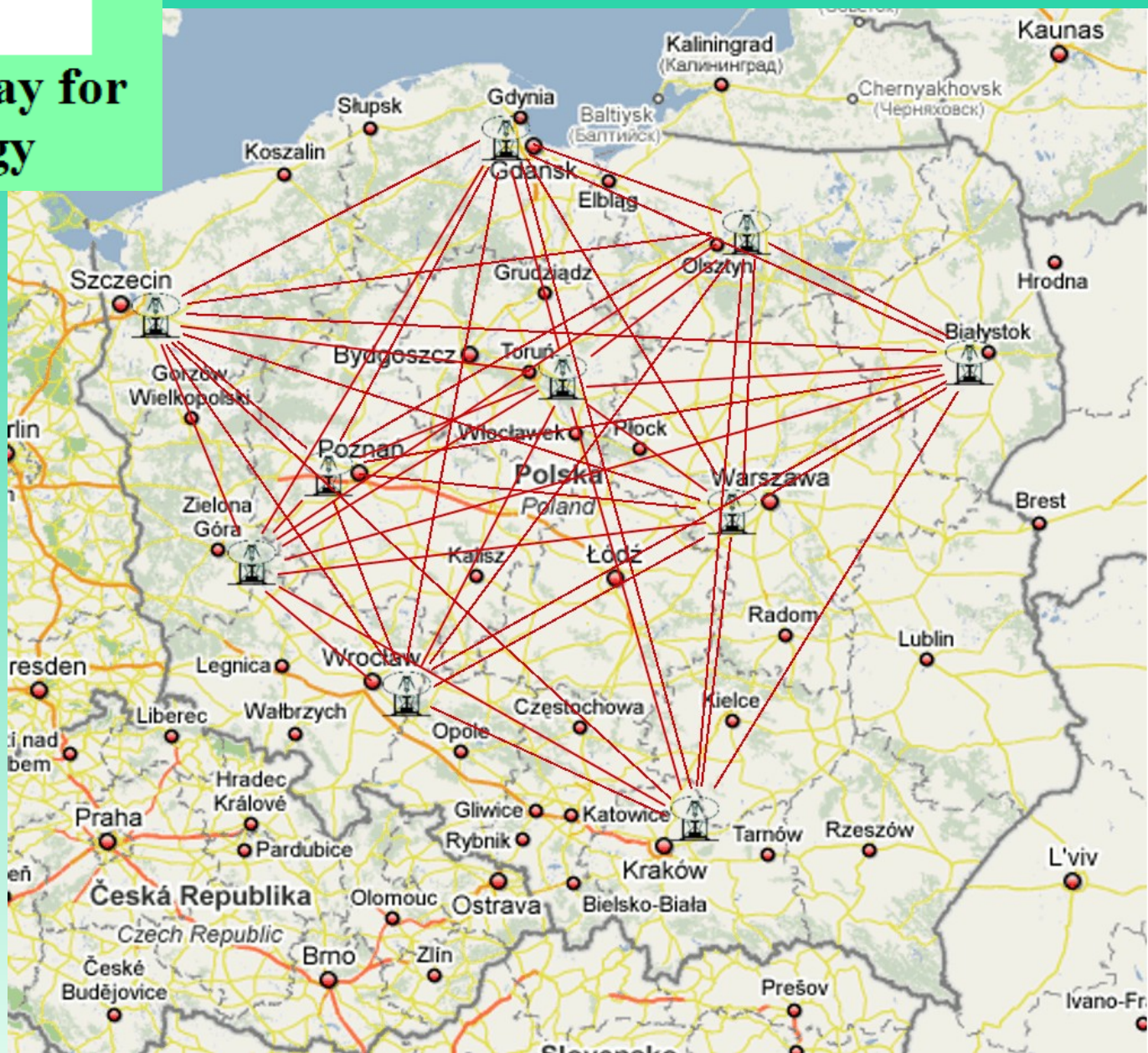
OCRA-F



PIAST

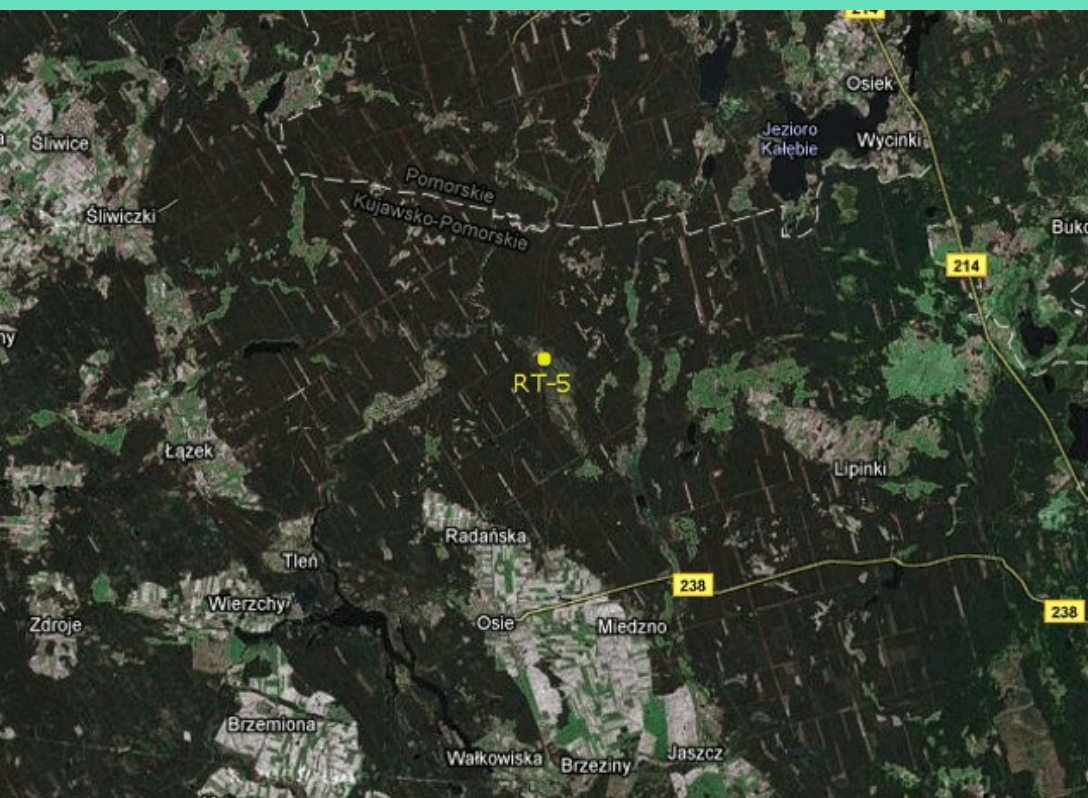
<http://www.astro.uni.torun.pl/piast/index.php>

**Polish Interferometer Array for
Science and Technology**



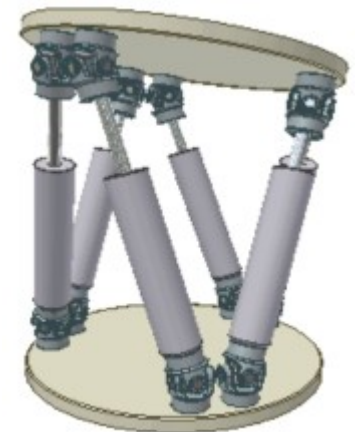
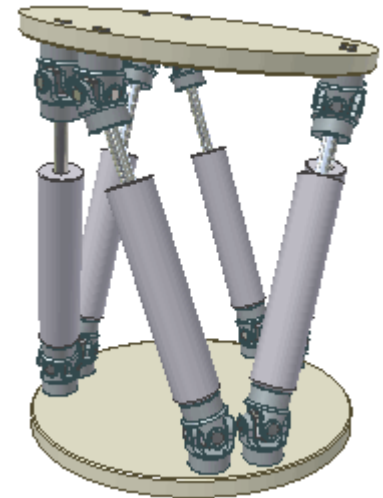
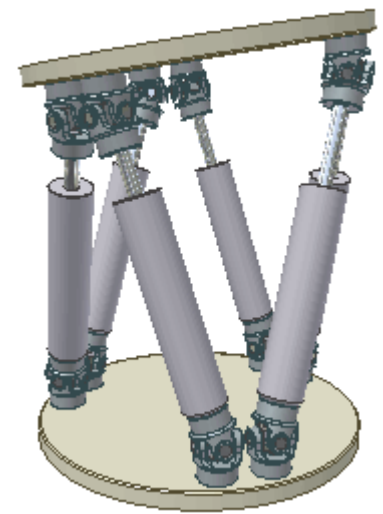
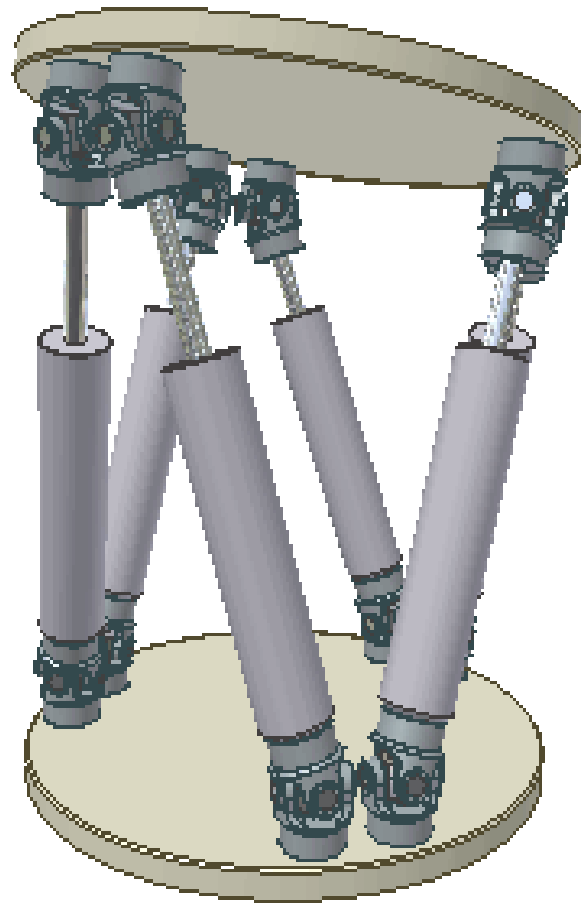
Nowy toruński radioteleskop (90-100 m)

<http://www.astro.uni.torun.pl/rt5.php>



Podstawowe parametry techniczne i eksploatacyjne proponowanego 90m radioteleskopu

Parametry	Wielkość/typ	Uwagi
System optyczny	Cassegrain	
Średnica czaszy reflektora D	90 m	Paraboloida obrotowa
Ogniskowa głównego reflektora f	31,5m	
Światłosiła f/D	0,35	
Lustro wtórne średnica d	9 m	Hiperboloida obrotowa
Efektywna ogniskowa F	273 m	
Położenie ognika wtórnego	3 m	Powyżej powierzchni czaszy
Precyzja wykonania powierzchni	0,5 mm	RMS
Zakres ruchów anteny (w wysokości)	25 - 90 stopni	Pochylenie w każdym kierunku
Precyzja sterowania	0.002 stopnia	Pozycjonowanie i śledzenie
Maksymalna prędkość ruchu	30 deg/min	Ruch tylko w wysokość
Całkowita waga	~1000 ton	
Pole widzenia (straty < 5%)	1-2 stopni	Zależnie od wielkości kamery
Zakres częstotliwości pracy	1-22 GHz	W ognisku wtórnym
Rozdzielczość kątowna	2,7 - 0,5 arcmin	W zakresie 5 - 22 GHz
Czułość radioteleskopu przy 1 sek integracji	1,2 mJy	Dla kontinuum, 5 x RMS
Czułość radioteleskopu dla 1 godz. integracji	20 mikroJy	j.w
Temperatura szumowa systemu odbiorczego	25-35 K	W zakresie 5 -22 GHz
Konfuzja (ograniczenie rozdzielczości kątowej)	0,3 - 0,1 mJy	Dla 5 - 22 GHz
Liczba niezależnych odbiorników w macierzy odb.	49 (100)	I etap (docelowo)
Liczba niezależnych torów odbiorczych	784 (1600)	
Rozdzielczość spektralna	1 kHz	
Rozdzielczość czasowa	0,1 msec	
Rodzaj cyfrowych „backendów”	FPGA	Projekt FP7 UNIBOARD
Lokalizacja	Dębowiec	53°39'31,4"N 18°21'43,8"E
Transmisja danych do obserwatora	>10 Gb/s	Dedykowana sieć światłowodowa



**Koncepcja sterowania czasą nowego
90-metrowego radioteleskopu**